

# On Time-Triggered Ethernet in NASA's Lunar Gateway

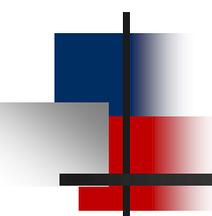
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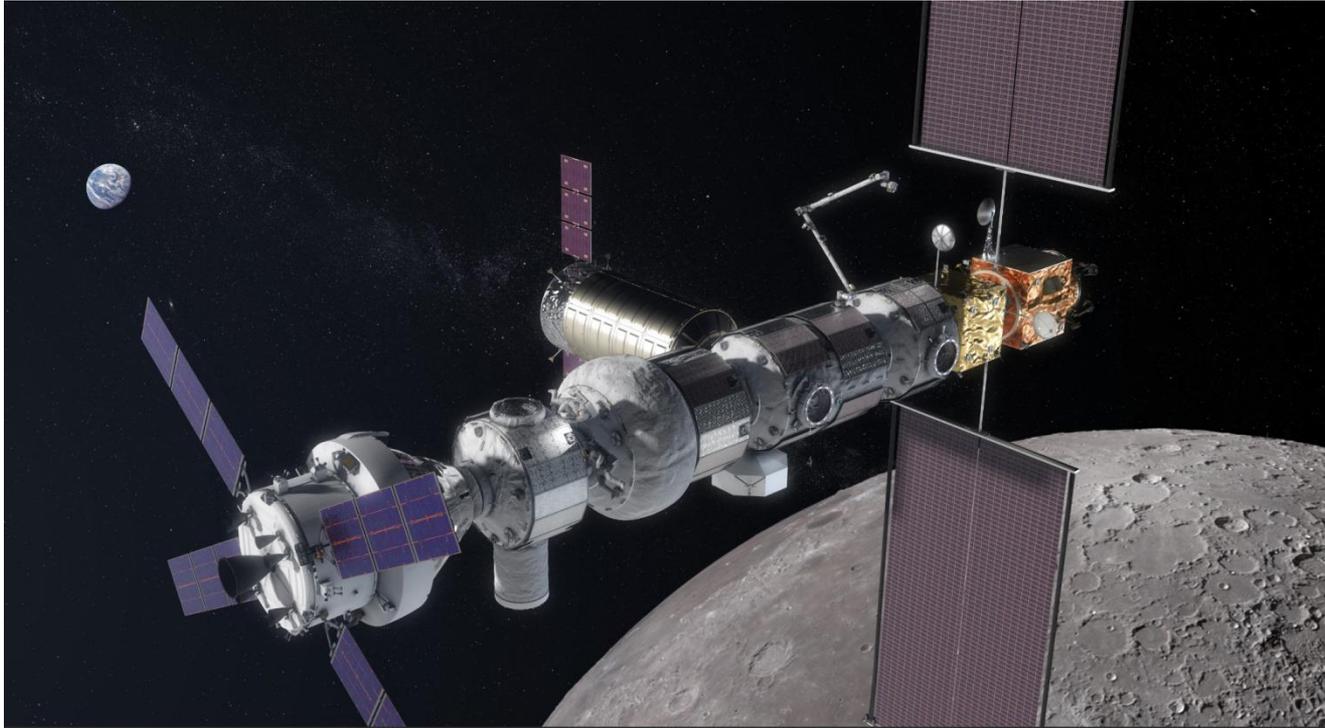
# Agenda

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- Introduction to Gateway
- Time-Triggered Ethernet (TTE) backbone
- TTE, A Fault-Tolerant Interconnect
- TTE, An Integration Framework
- A Unique Challenge, Classical Ethernet
- Conclusion

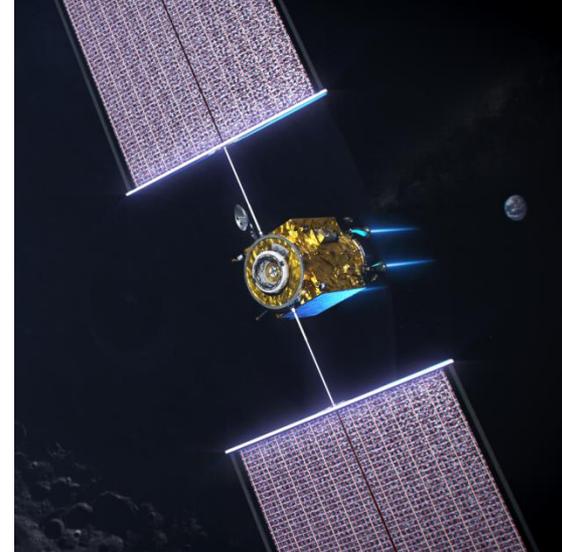
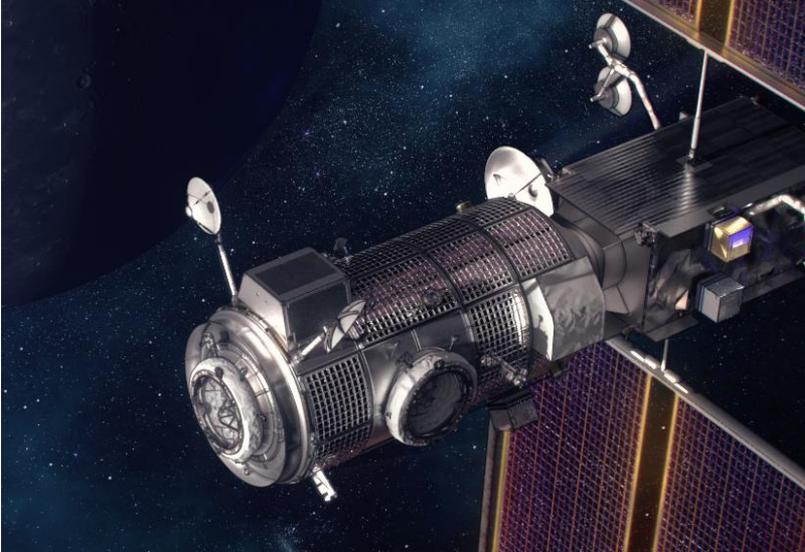
# Introduction to Gateway

- Lunar outpost under development to support a sustainable human presence on and around the moon



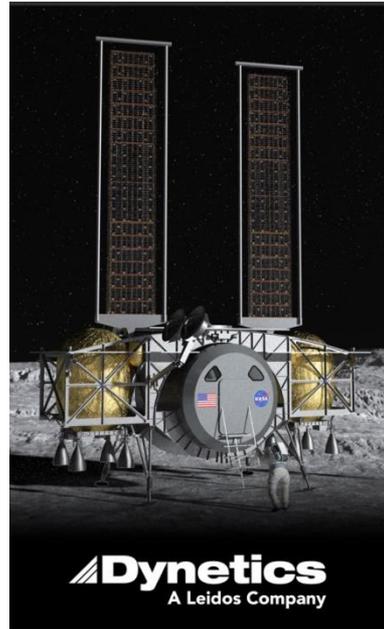
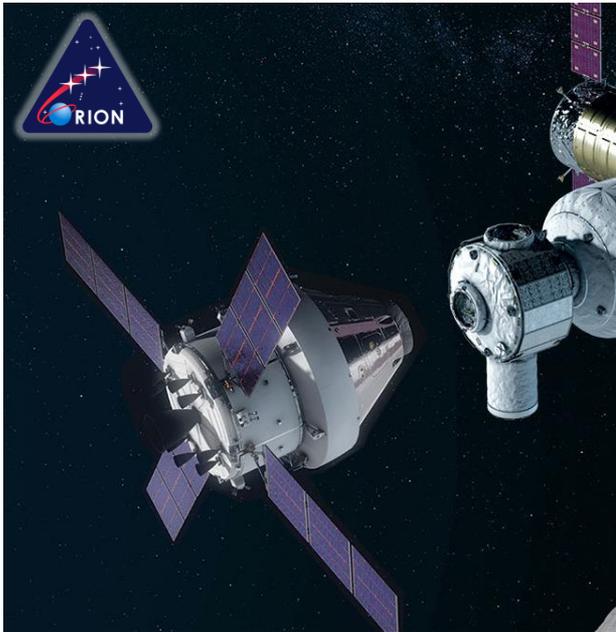
# Introduction to Gateway

- Made up of multiple modules:
  - **Power and Propulsion Element (PPE)**
    - Solar electric propulsion spacecraft that will provide power, communications, and attitude control
  - **Habitation and Logistics Outpost (HALO)**
    - Provides life support, command and control, energy storage and power distribution

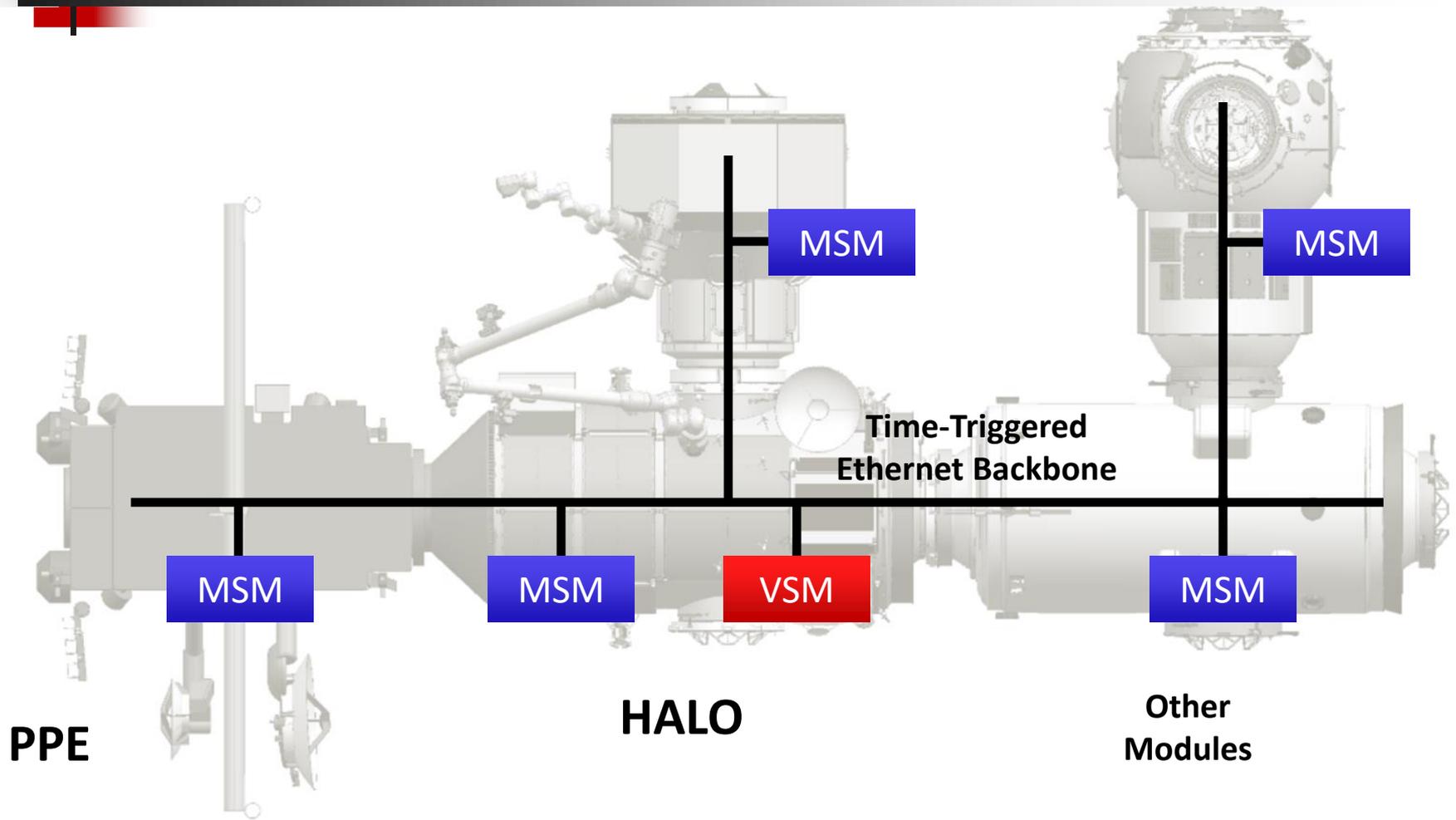


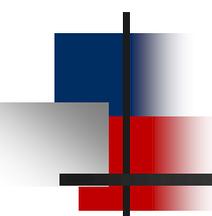
# Introduction to Gateway

- Visiting vehicles:
  - Orion, Gateway Logistic Services, Human Landing System (HLS)



# Introduction to Gateway





# Agenda

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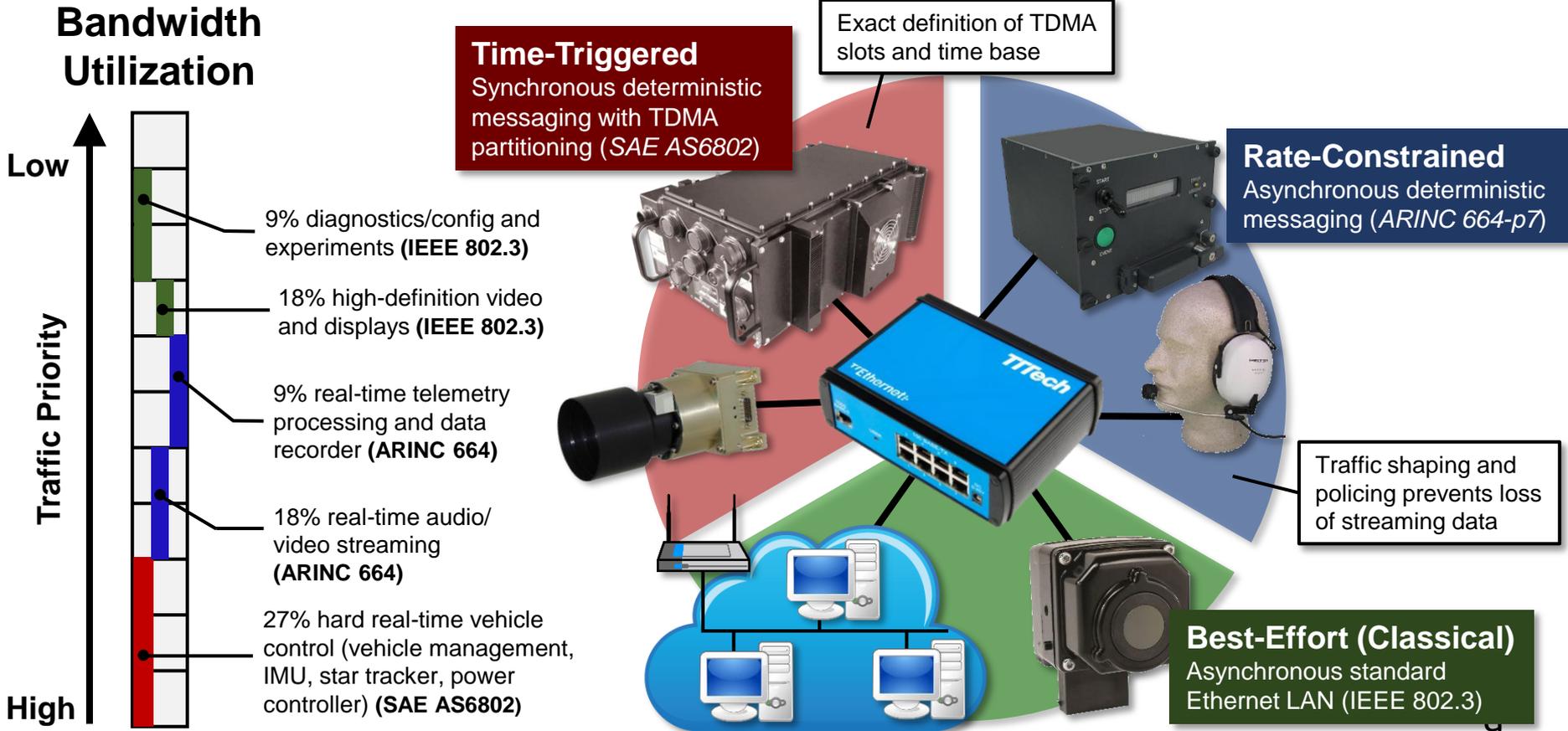
- Introduction to Gateway
- **Time-Triggered Ethernet (TTE) Backbone**
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# Competing Requirements

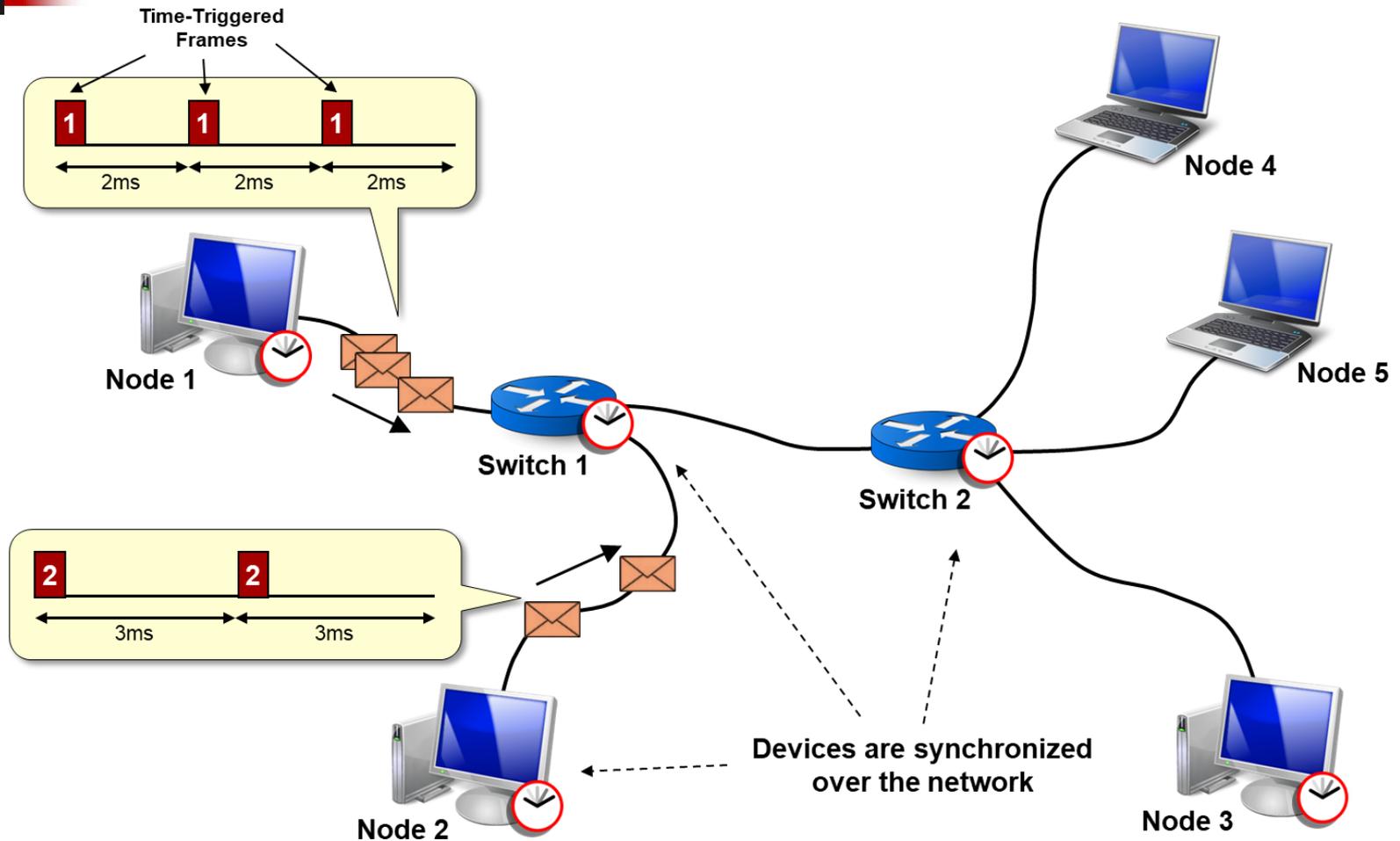
- A vehicle like GW puts conflicting requirements on the network
  - It is both a safety-critical vehicle and a research platform
- Control-centric systems need networks with:
  - High integrity and availability
  - Worst case bounded latency and jitter
- Science-centric systems need networks with:
  - Compatibility with COTS devices
  - High throughput
  - Flexibility and expandability
- Often the same computer needs both:
  - E.g. IMA – functions with different criticalities on the same computer



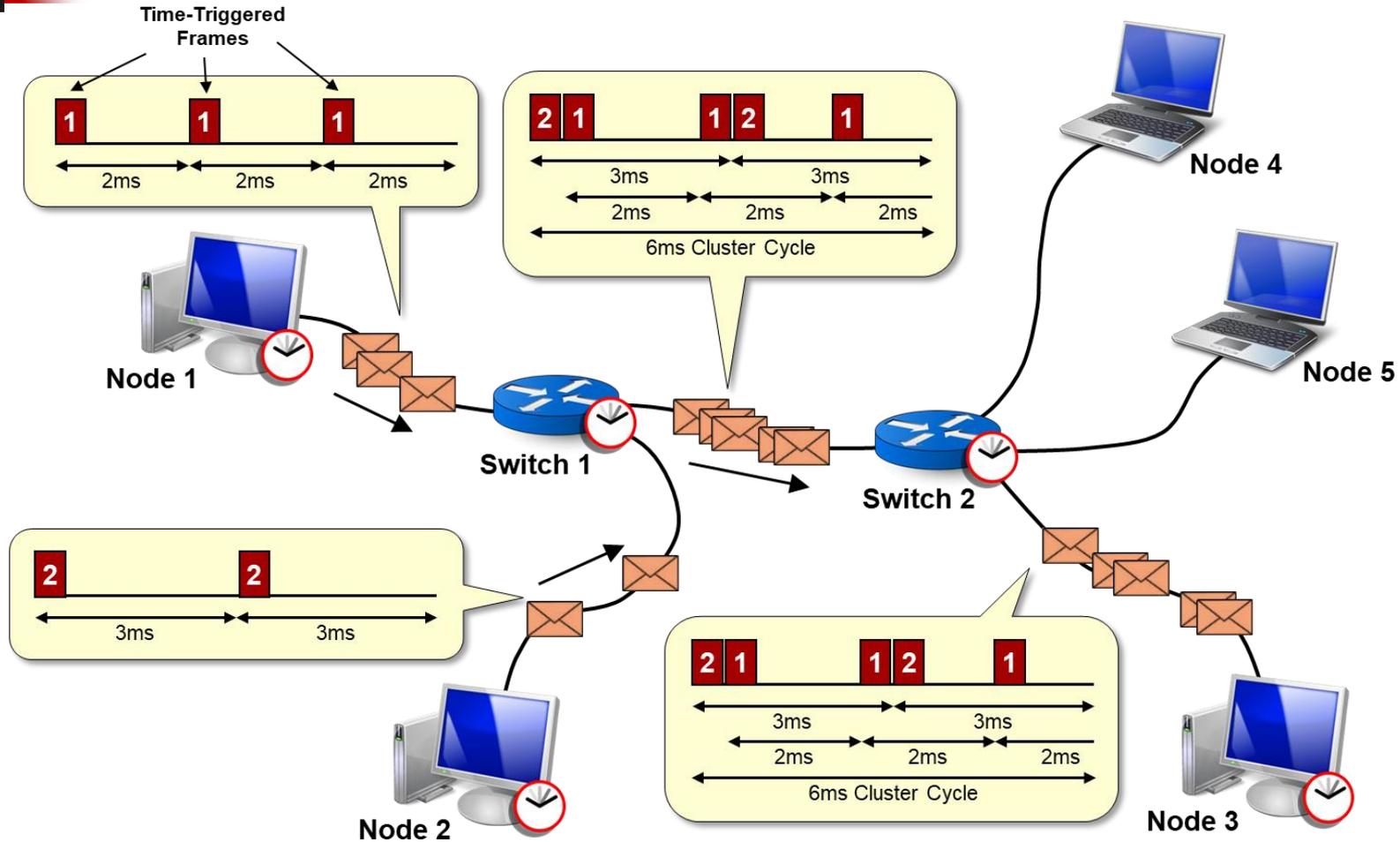
# Time-Triggered Ethernet (TTE)



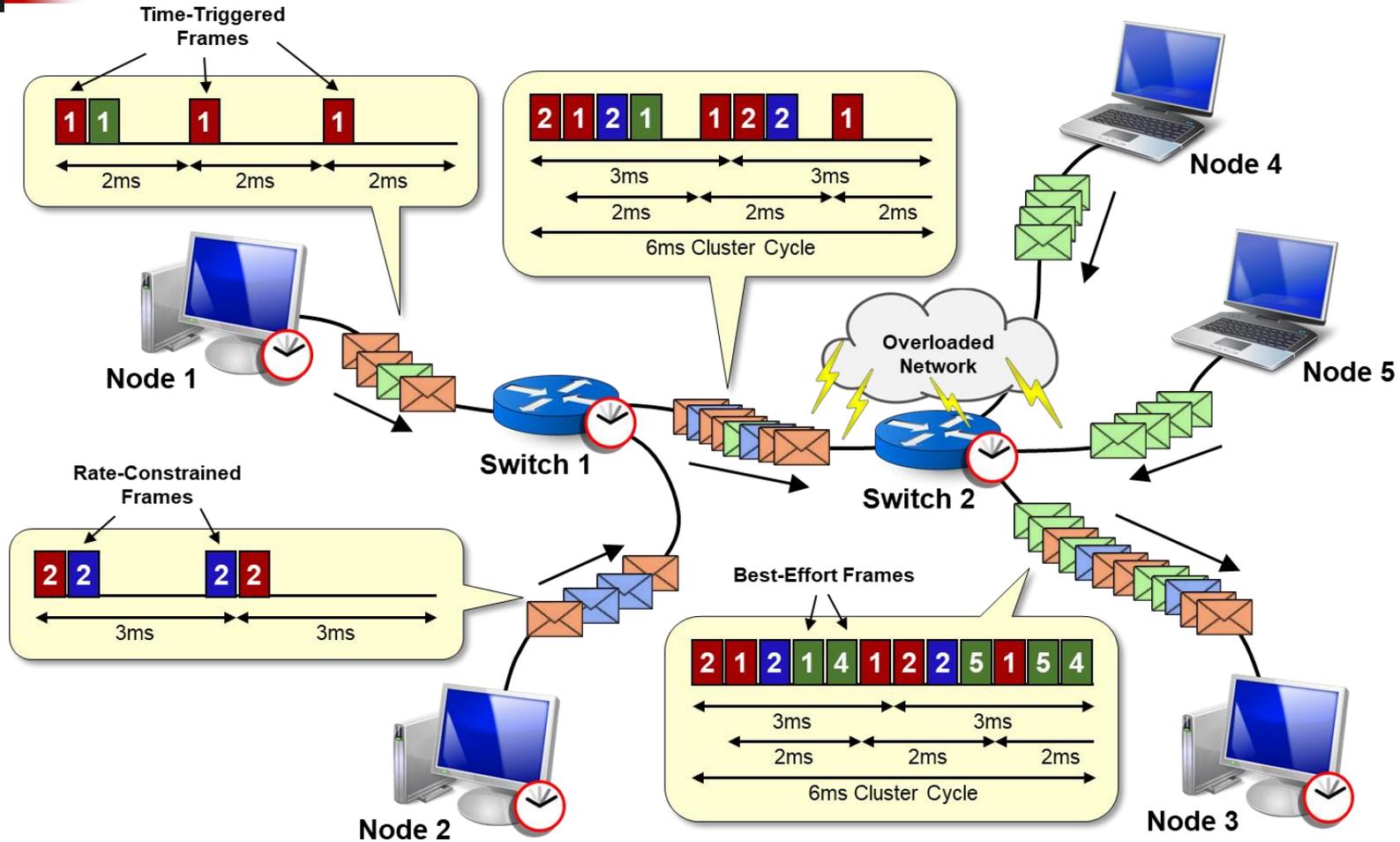
# TTE Traffic Integration



# TTE Traffic Integration

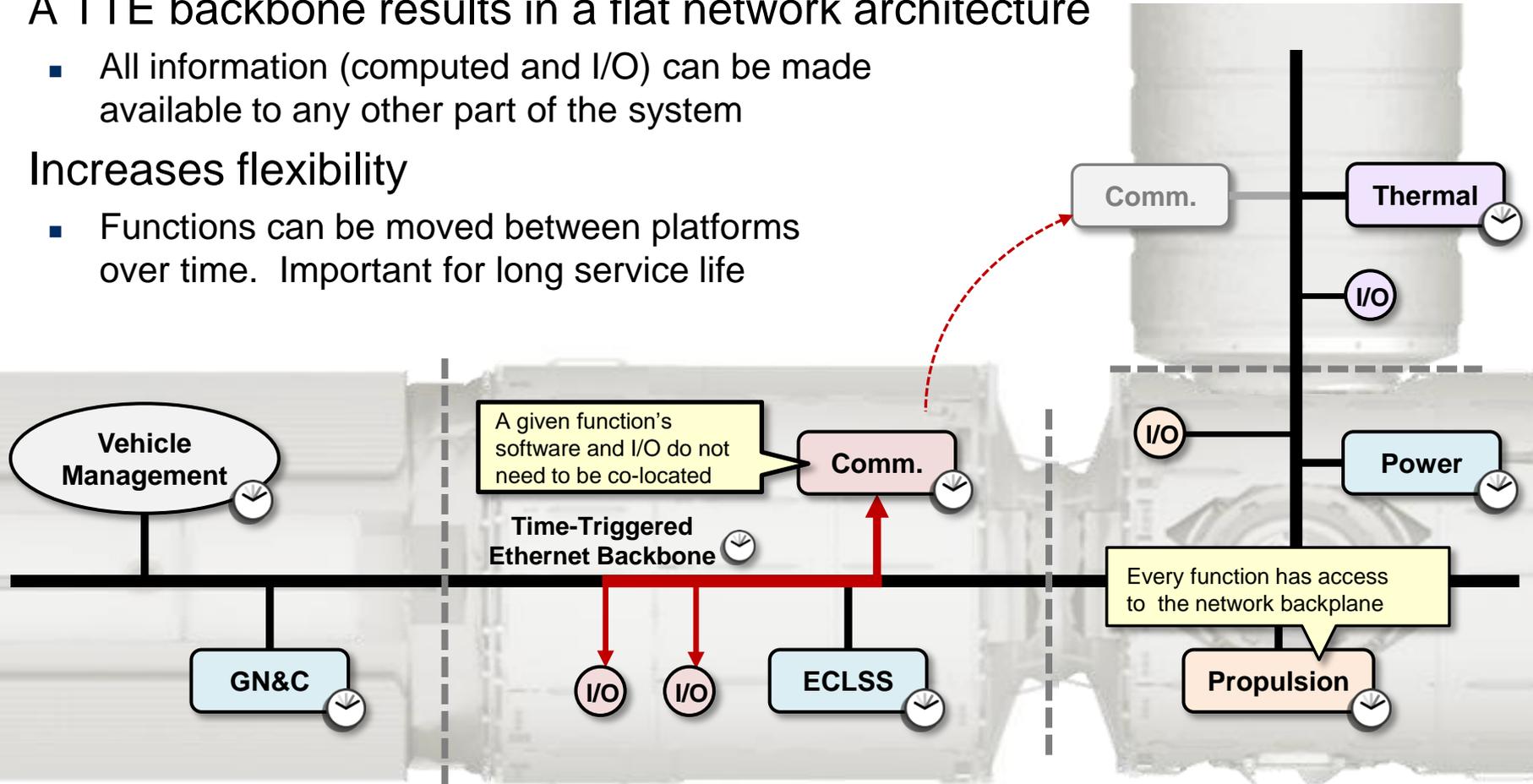


# TTE Traffic Integration



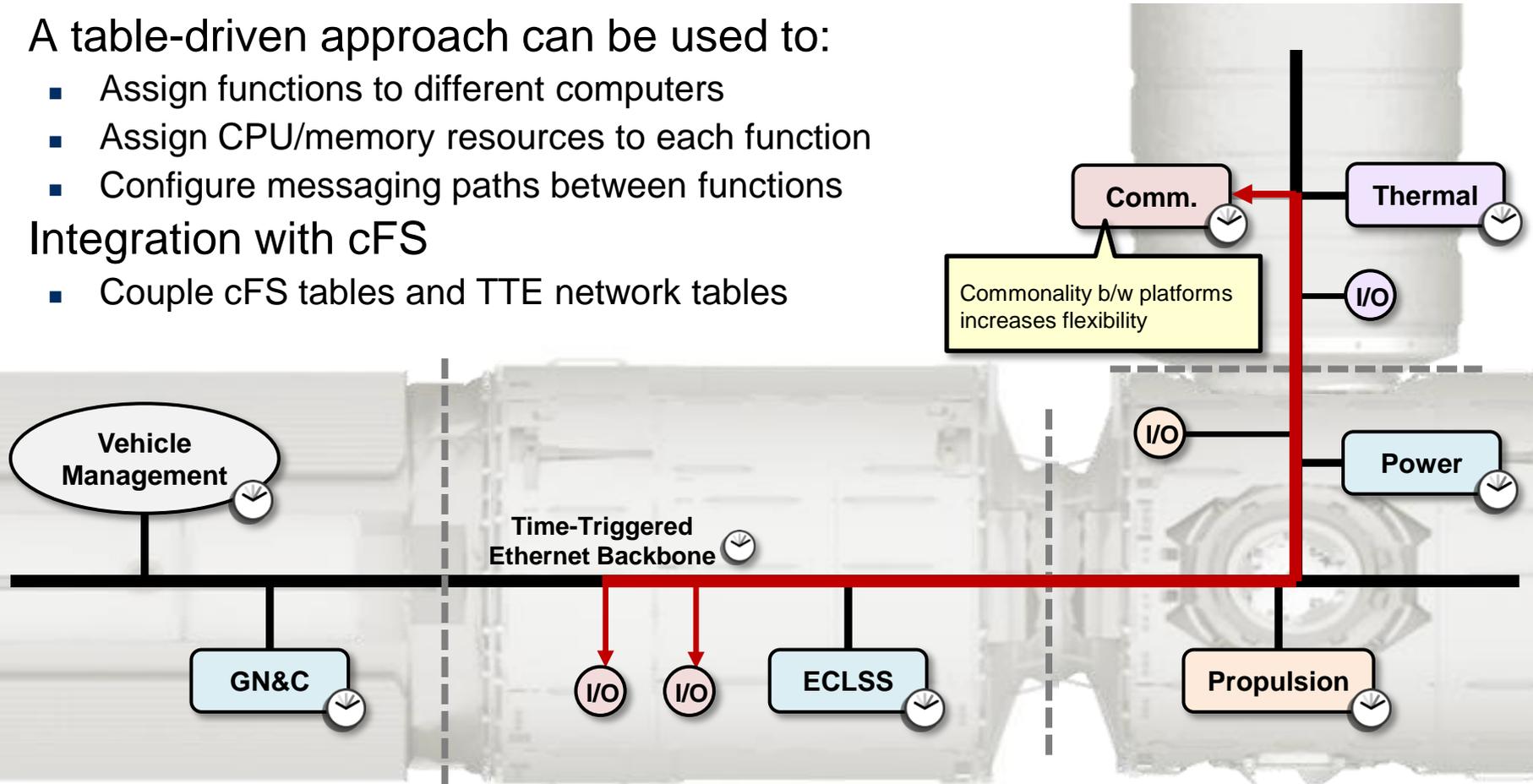
# A Flat Network Architecture

- A TTE backbone results in a flat network architecture
  - All information (computed and I/O) can be made available to any other part of the system
- Increases flexibility
  - Functions can be moved between platforms over time. Important for long service life

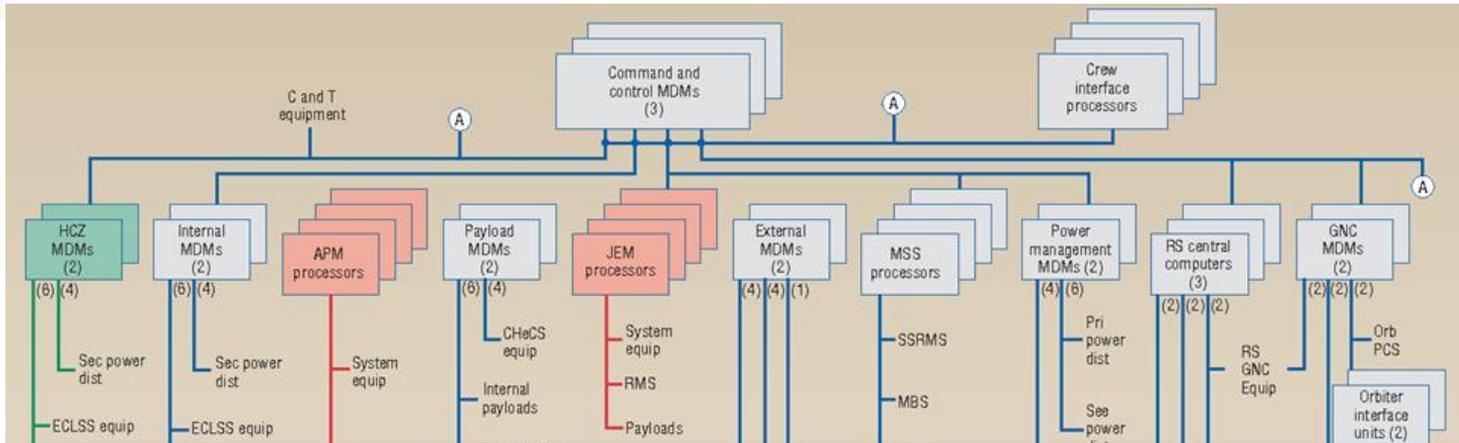


# A Flat Network Architecture

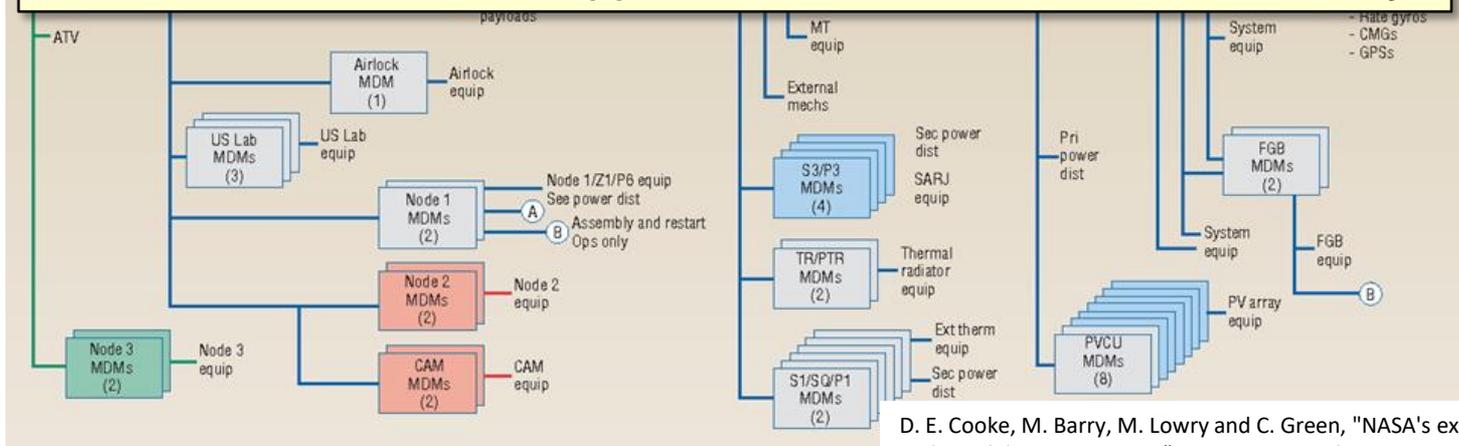
- A table-driven approach can be used to:
  - Assign functions to different computers
  - Assign CPU/memory resources to each function
  - Configure messaging paths between functions
- Integration with cFS
  - Couple cFS tables and TTE network tables



# A Flat Network Architecture

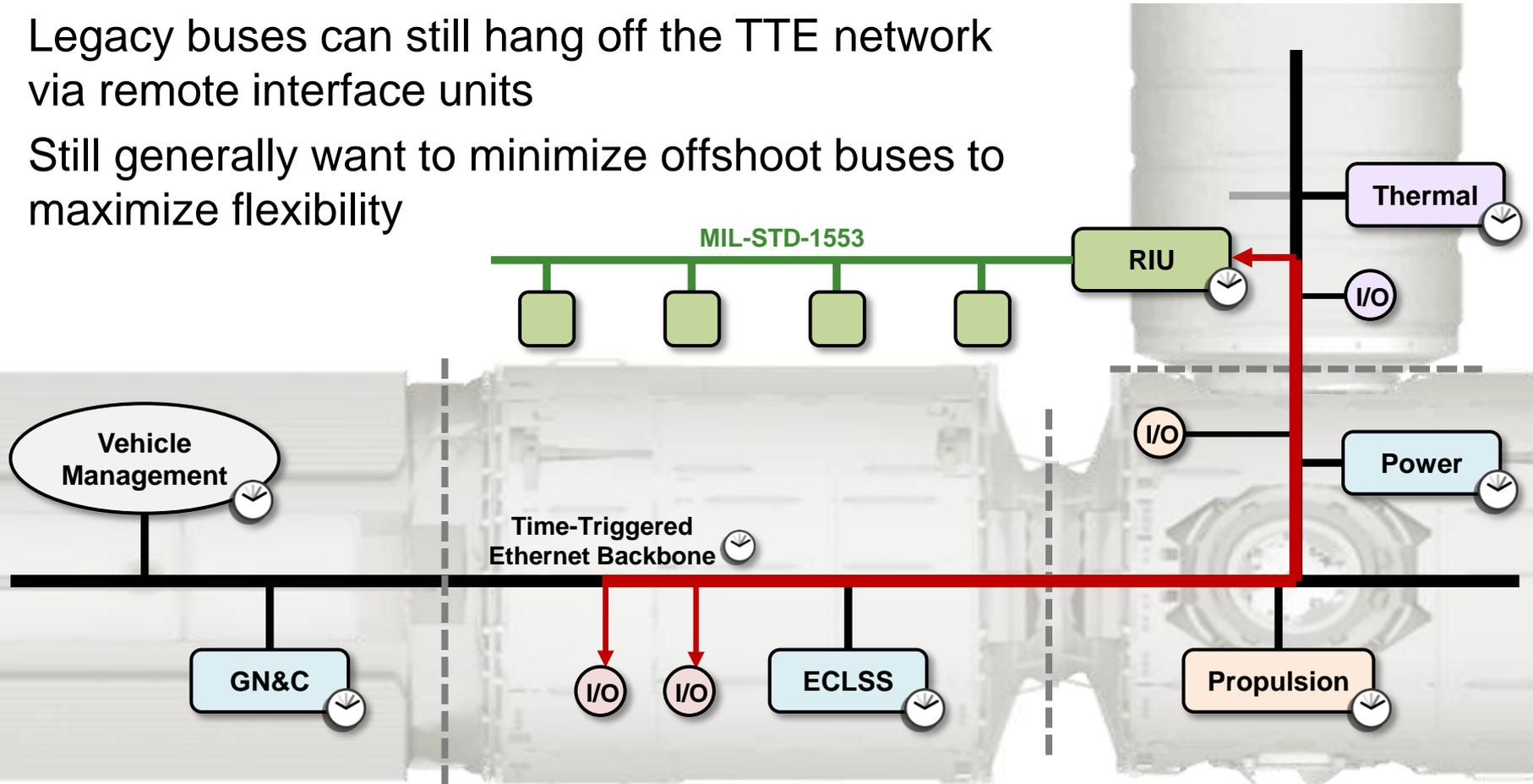


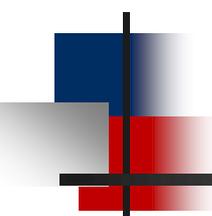
ISS uses a hierarchical approach that lacks this sort of flexibility



# A Flat Network Architecture

- Legacy buses can still hang off the TTE network via remote interface units
- Still generally want to minimize offshoot buses to maximize flexibility





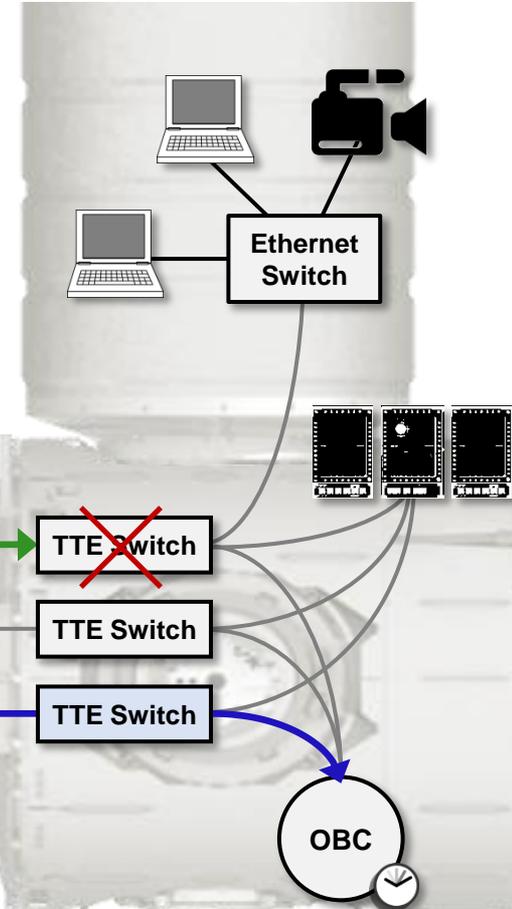
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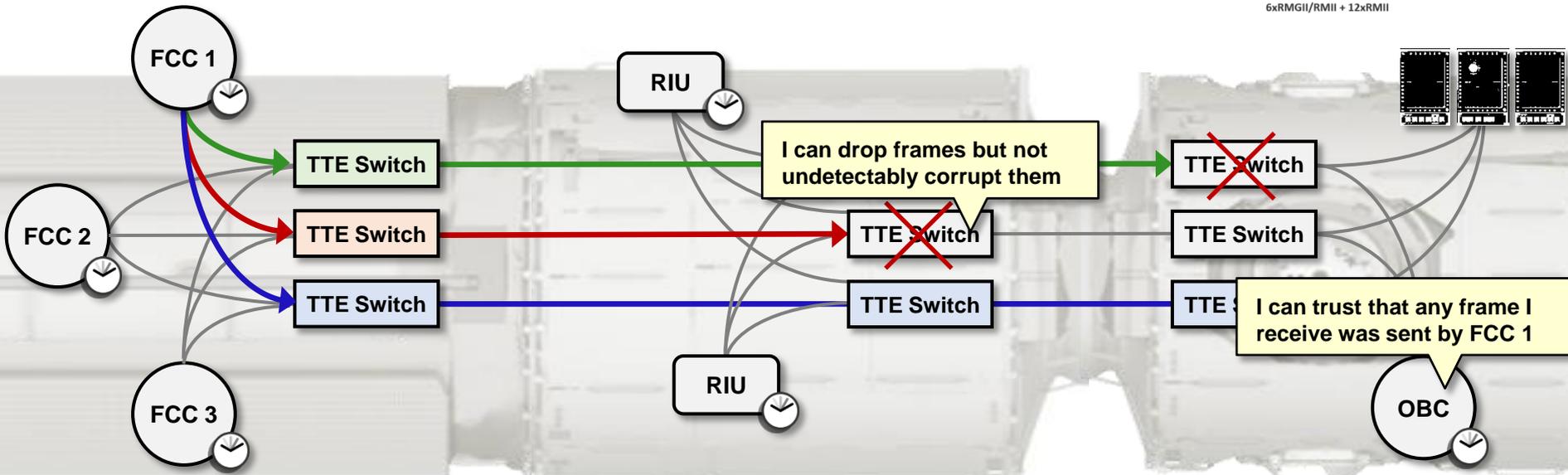
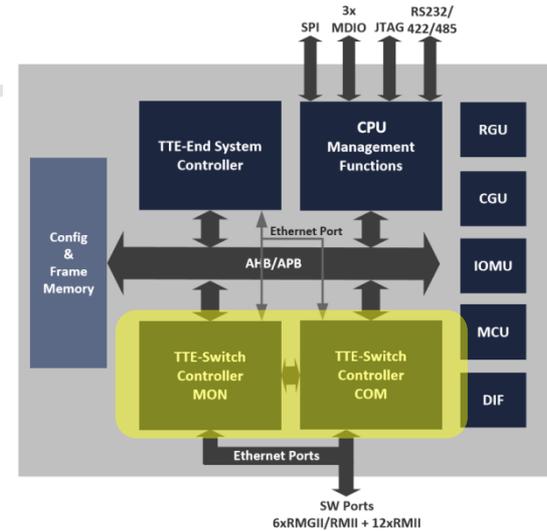
# TTE Network Availability

- Network availability comes from 3 planes
- Traffic goes over all planes simultaneously
- Tolerant to failures in any 2 planes



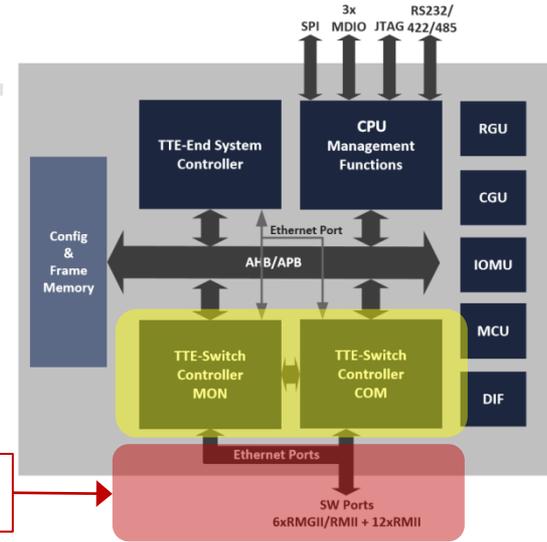
# TTE Network Integrity

- High-integrity switch design prevents undetectable frame corruption
- Uses COM/MON with two switch IPs

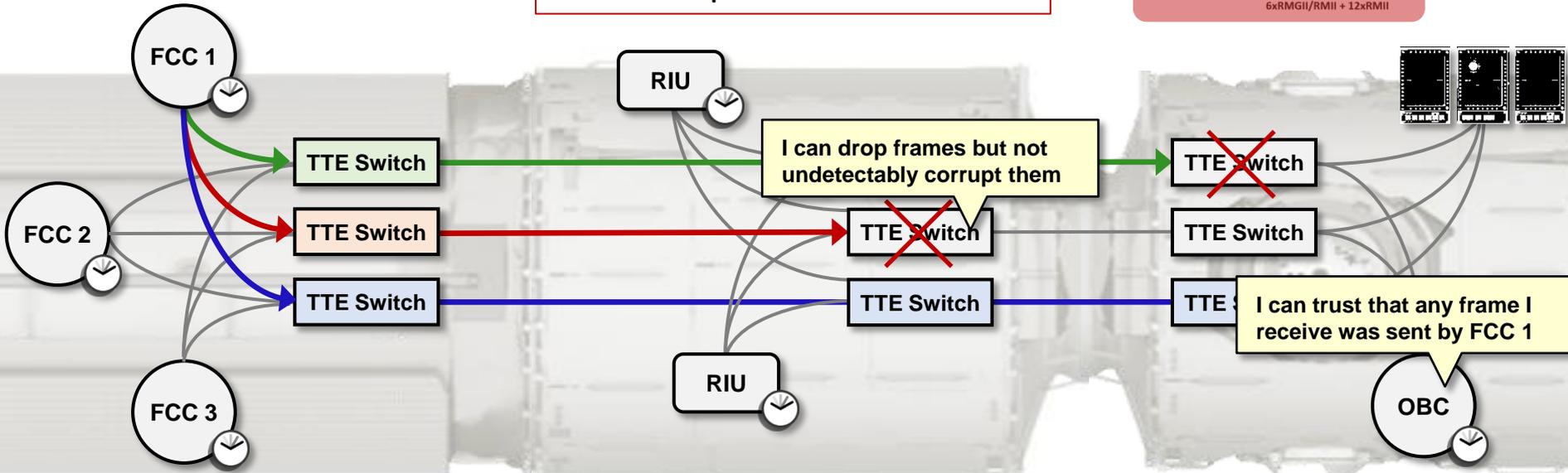


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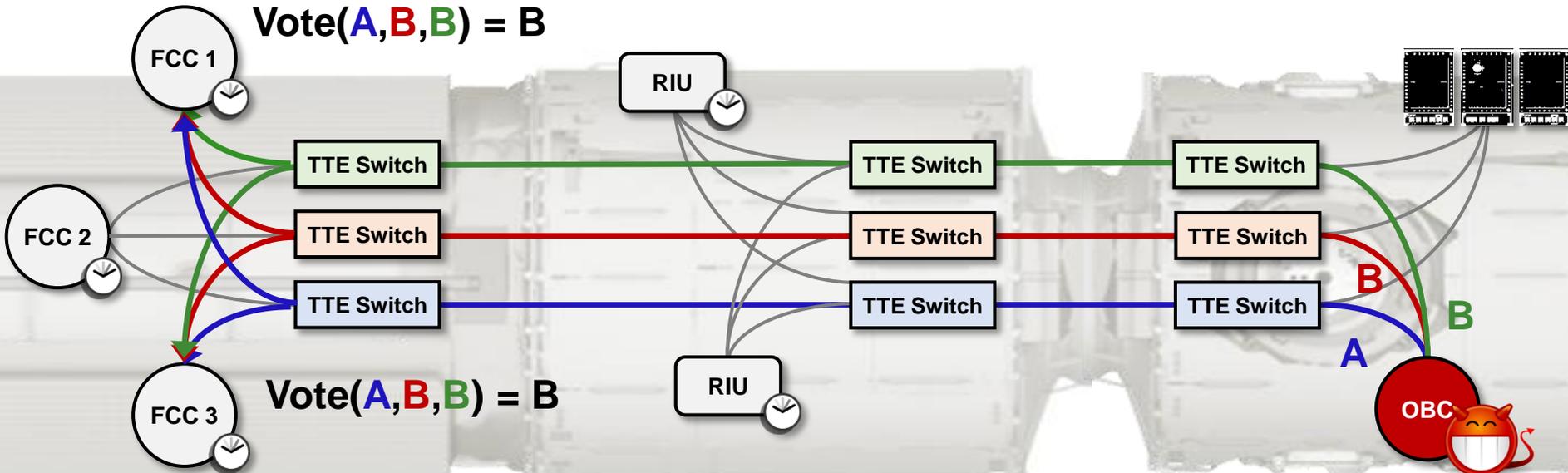
Still susceptible to faults here





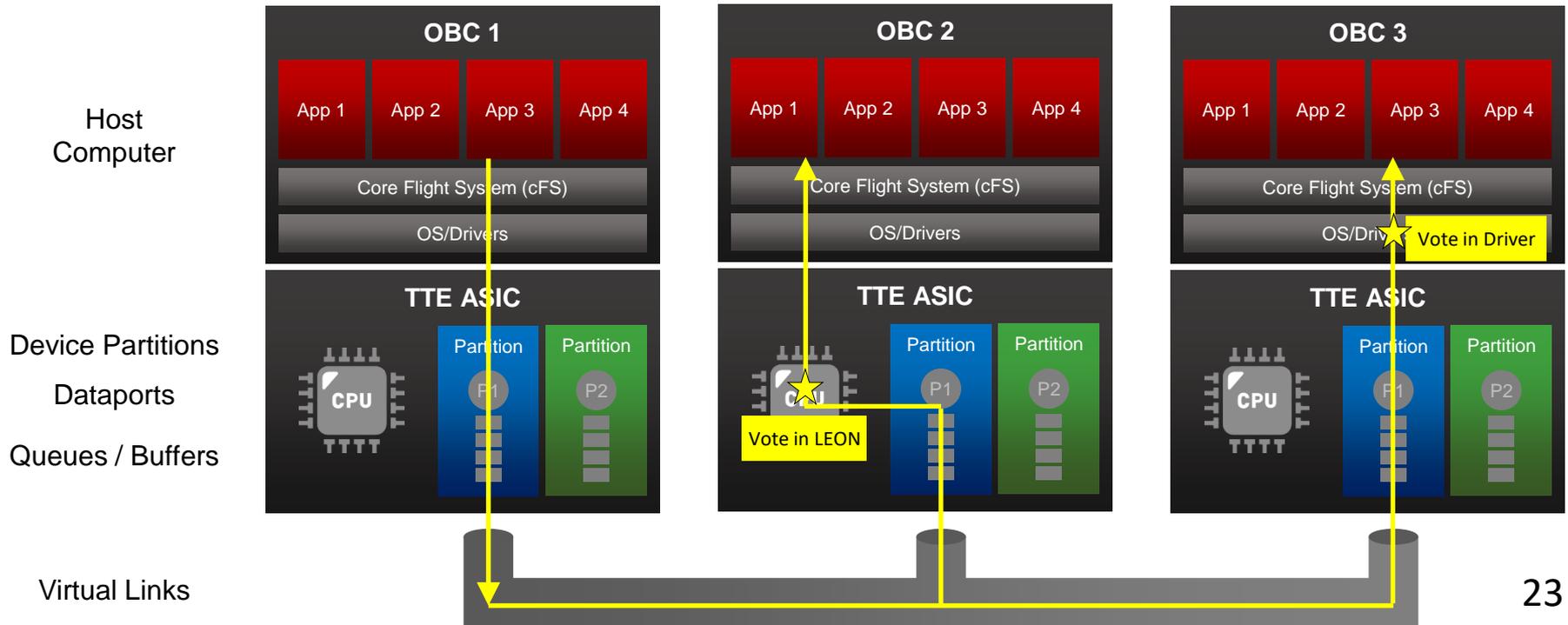
# TTE Asymmetric Transmissions

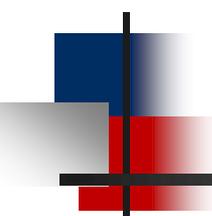
- Return all redundant frames to the host
- Hybrid majority vote (exclude manifest faulty frames)
- Guarantees all correct receivers deliver the same message



# Voting Realization

- Voting is configurable on a VL-by-VL basis – groups redundant frames by arrival time
- Can be performed in the Leon CPU in TTE ASIC, or in the driver software





# TTE Broadcast Channel

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- Lets you realize a **broadcast channel** abstraction
- Given 1 faulty end system:
  - If the sender is correct and broadcasts  $v$ , all correct receivers get  $v$
  - All correct receivers deliver the same value
- Given 1 faulty end system + 1 faulty switch:
  - If the sender is correct and broadcasts  $v$ , all correct receivers get  $v$
  - All correct receivers that deliver a value deliver the same value

# TTE Broadcast Channel

- Lets you realize a **broadcast channel** abstraction

- Given 1 faulty end system:

- If the sender is correct and all correct receivers deliver a value, then all correct receivers deliver the same value.
- All correct receivers deliver the same value.

## Byzantine Agreement

- Given 1 faulty end system + 1 faulty switch:

- If the sender is correct and all correct receivers deliver a value, then all correct receivers deliver the same value.
- All correct receivers that deliver a value deliver the same value.

## Crusader Agreement

nice degradation

# Integrity/Availability Tradeoff

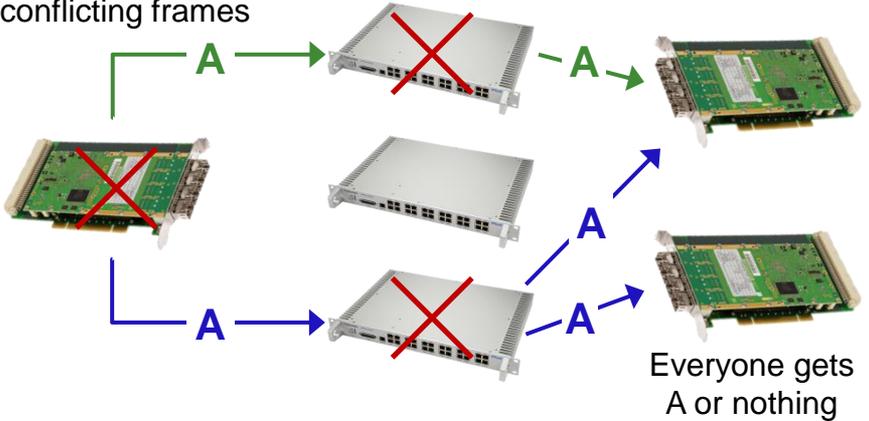
Orion (Phoenix IP)

Gateway (Pegasus IP)



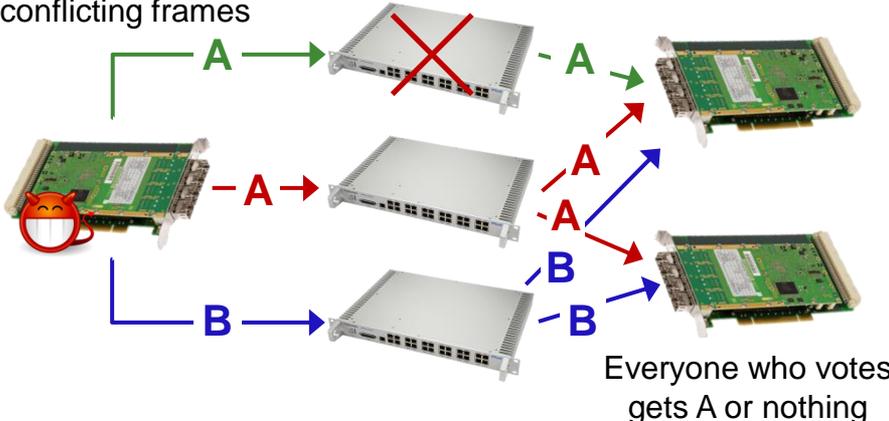
- Has high-integrity end systems
- Crusader broadcast channel with faulty ES and two faulty switches

Cannot send conflicting frames



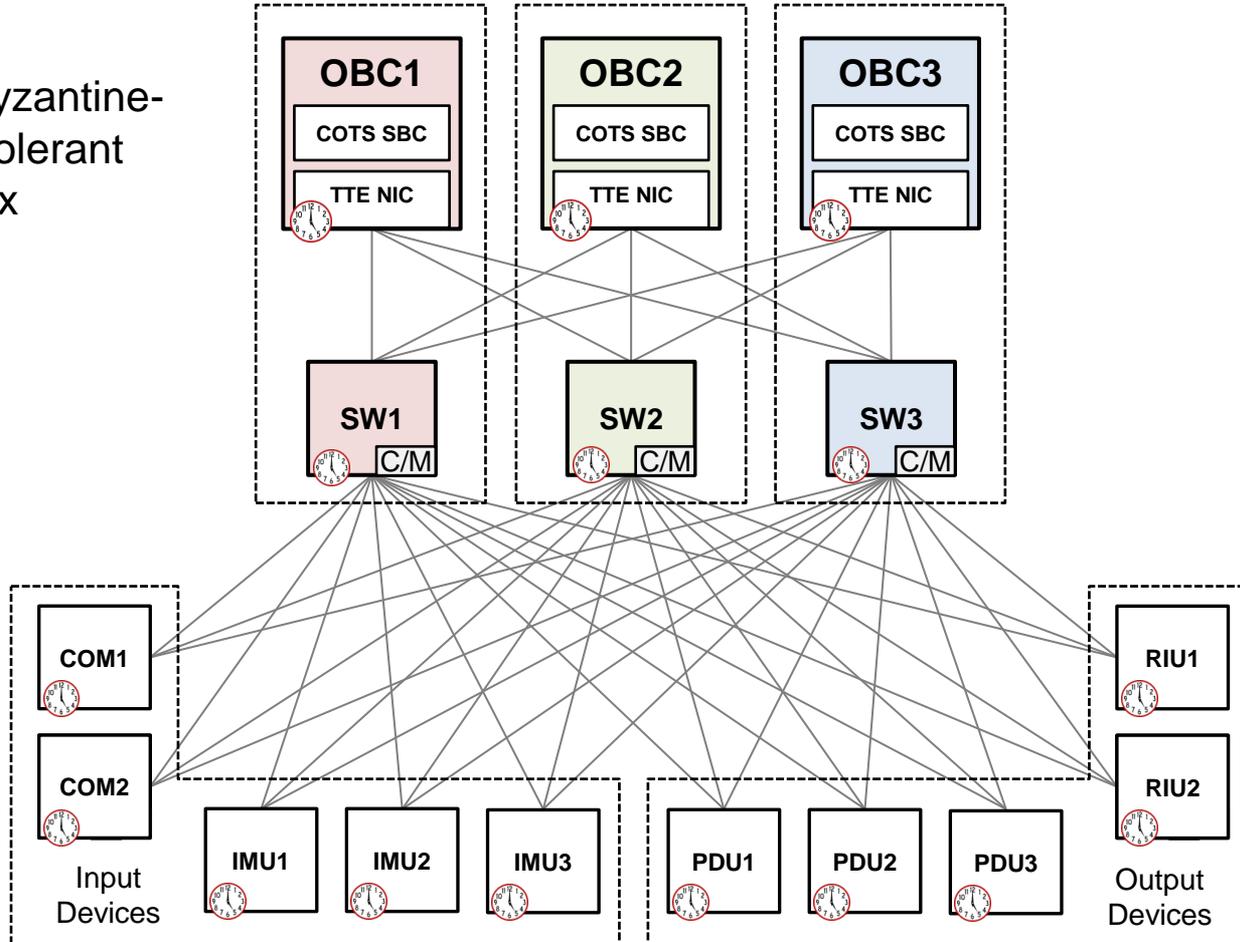
- Only standard-integrity end systems
- Crusader broadcast channel with faulty ES and one faulty switch

Can send conflicting frames



# Building on Broadcast Channels

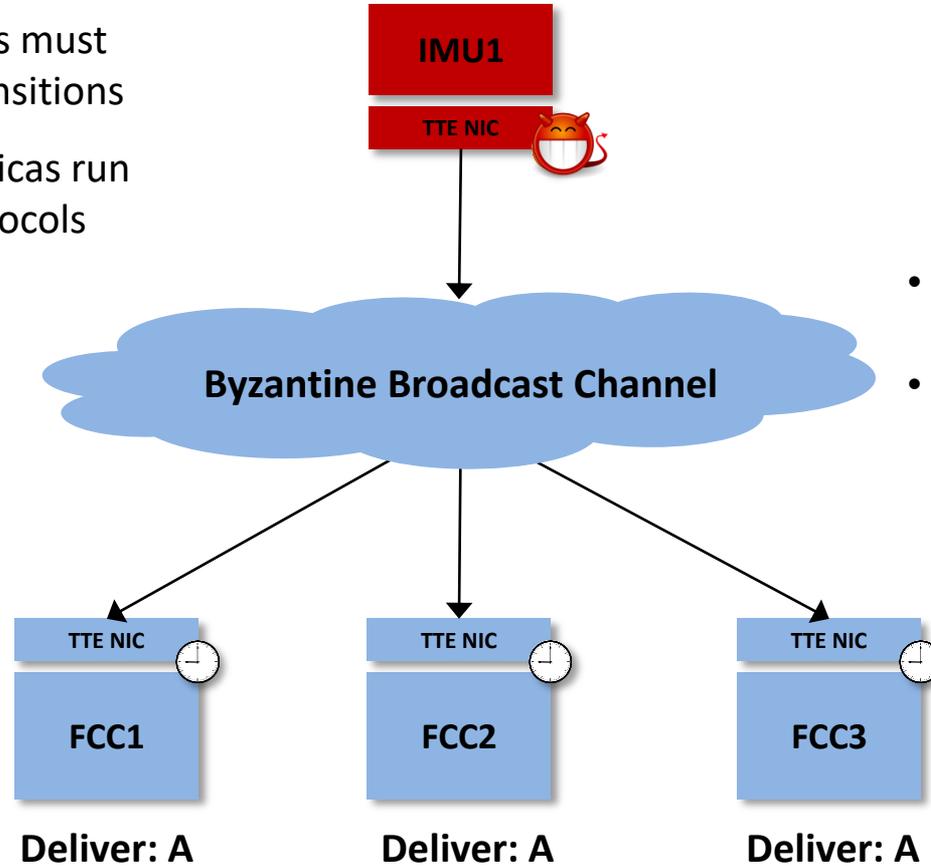
**Example:** 1 Byzantine-resilient fault-tolerant switched triplex



# Agreeing on External Data

**Key tenet of SMR:** Replicas must go through same state transitions

**How to accomplish?:** Replicas run Byzantine Agreement protocols on all input data

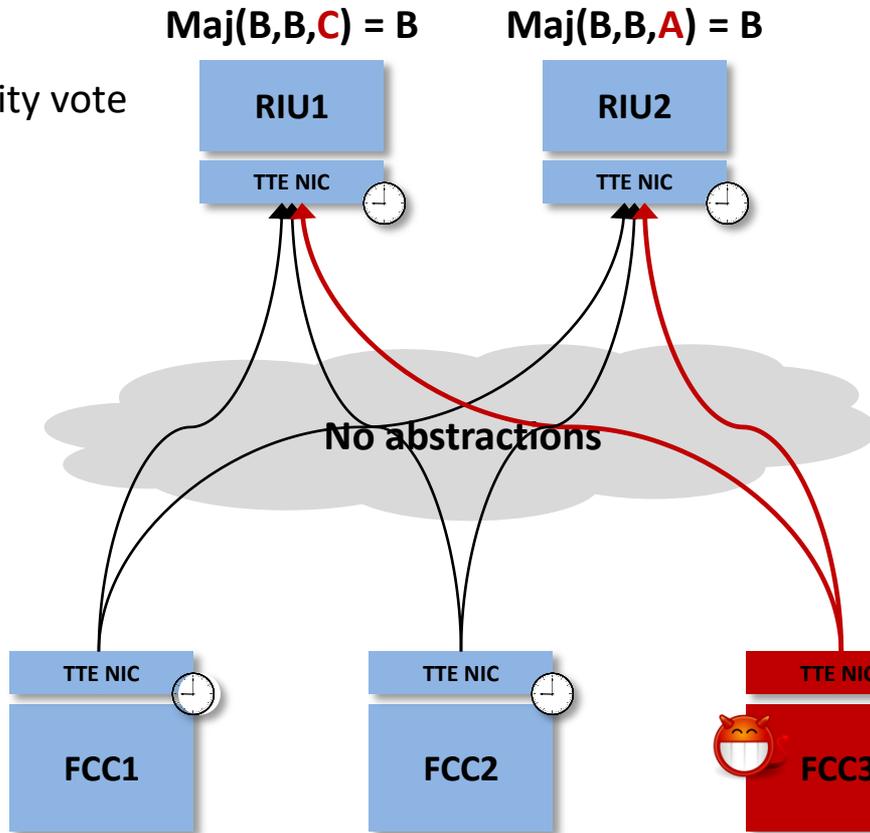


- Makes agreement on inputs (and state) trivial
- No explicit 2 round exchange needed

Must be consistent {

# Commanding Actuators

- 3 Receivers majority vote the commands



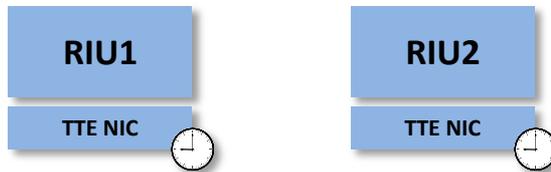
- 2 Receivers use normal first valid approach

- 1 A faulty NIC sends different frames to different planes

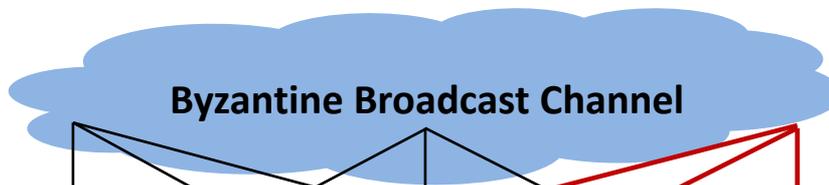
All correct replicas have same state so generate same output

# Fault Diagnosis

Happening Simultaneously ...



- 1 Outputs are reflected back via broadcast channel



- Uses same VLs as RIUs are reading

- 2 Replicas vote the **consistent** outputs from the replicas. Any replica that disagrees *is faulty*.

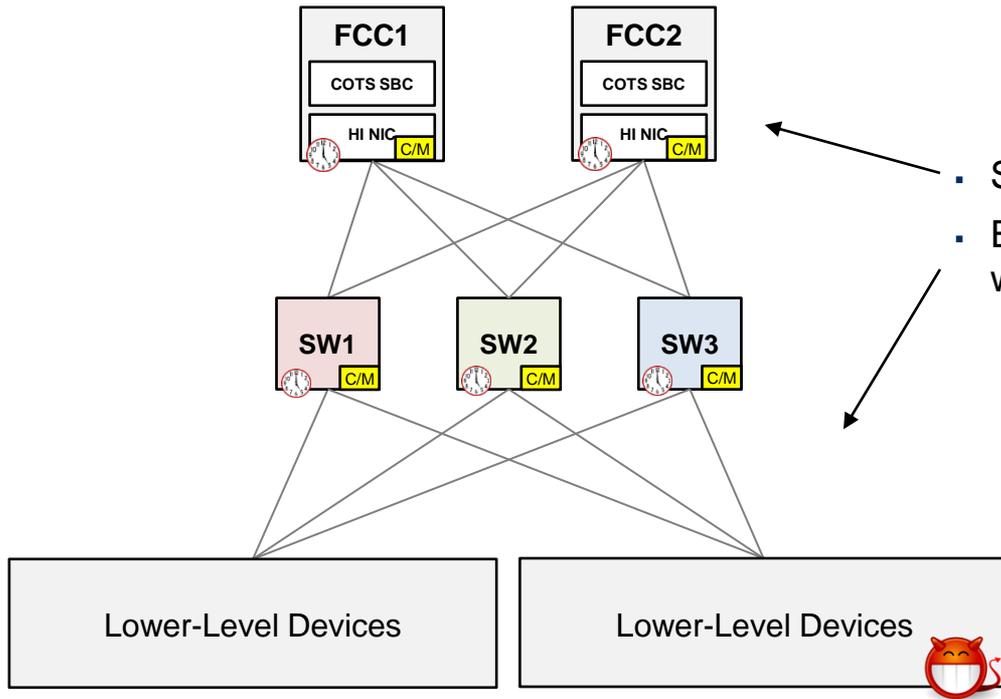


$$\text{Maj}(B, B, C) = B$$

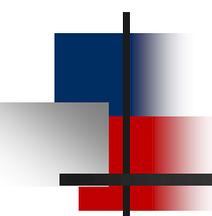
$$\text{Maj}(B, B, C) = B$$

# Building on Broadcast Channels

- Broadcast channels are applicable to many fault models and fault tolerance approaches
- E.g. A primary-backup system constrained to symmetric transmissive failures



- Still need to maintain consistent internal state
- Even if OBC1/2 can be assumed to fail in benign ways, the lower-level devices may not



# Agenda

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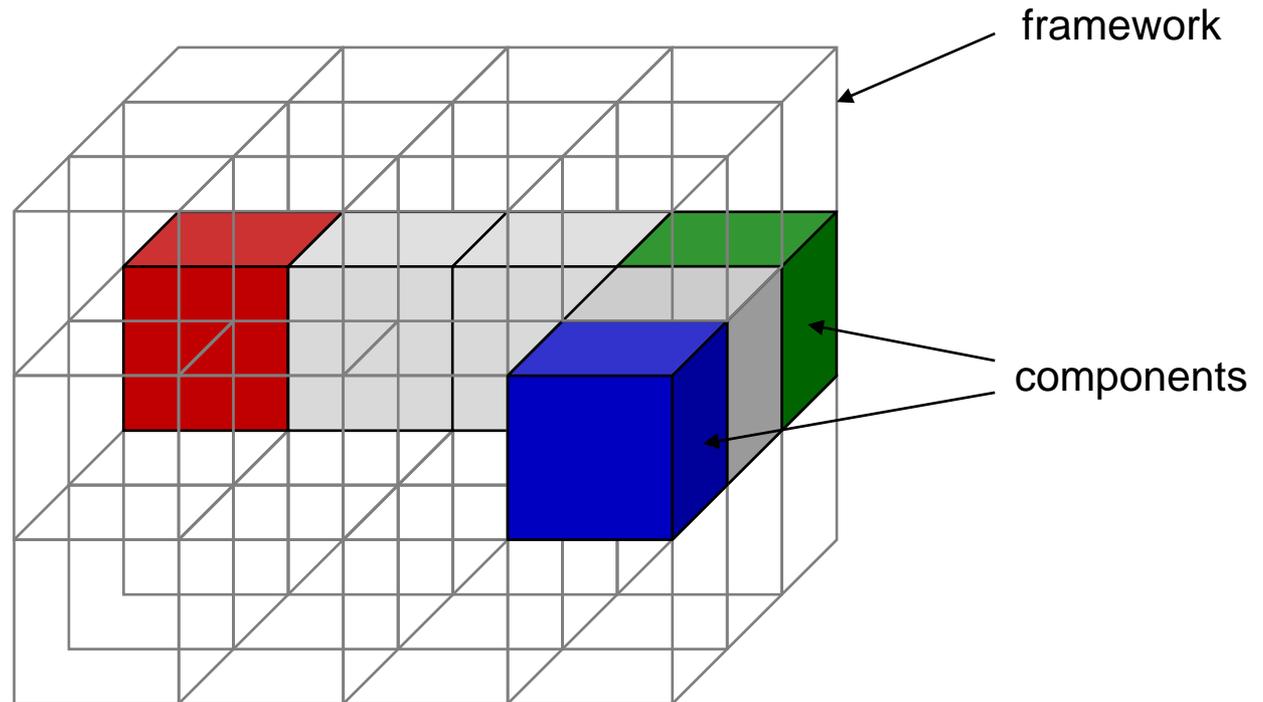
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# TTE: It's a Framework

- TTE is not just an interconnect, it is an **integration framework**

Framework provides the supporting structure for integrating components into the system

- Components can rely on the framework
- Framework doesn't rely on the components



# TTE: It's a Framework

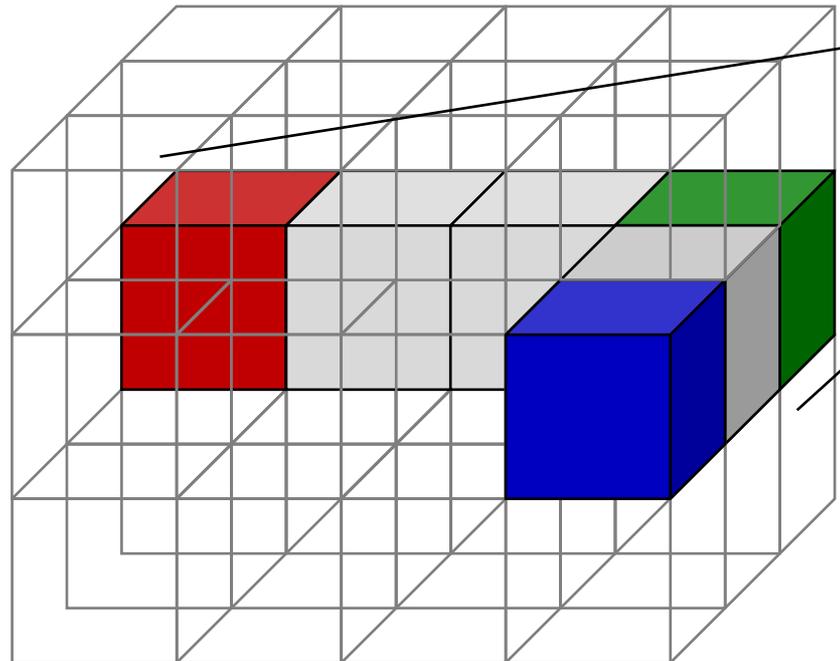
- TTE is not just an interconnect, it is an **integration framework**

TTE provides multiple formally verified services:

- Clock synchronization
- Clique detection
- Group membership
- Startup and Restart

... Which in combination provide services to the components (e.g. SW, subsystems):

- Partitioned Messaging
- Scheduled Execution

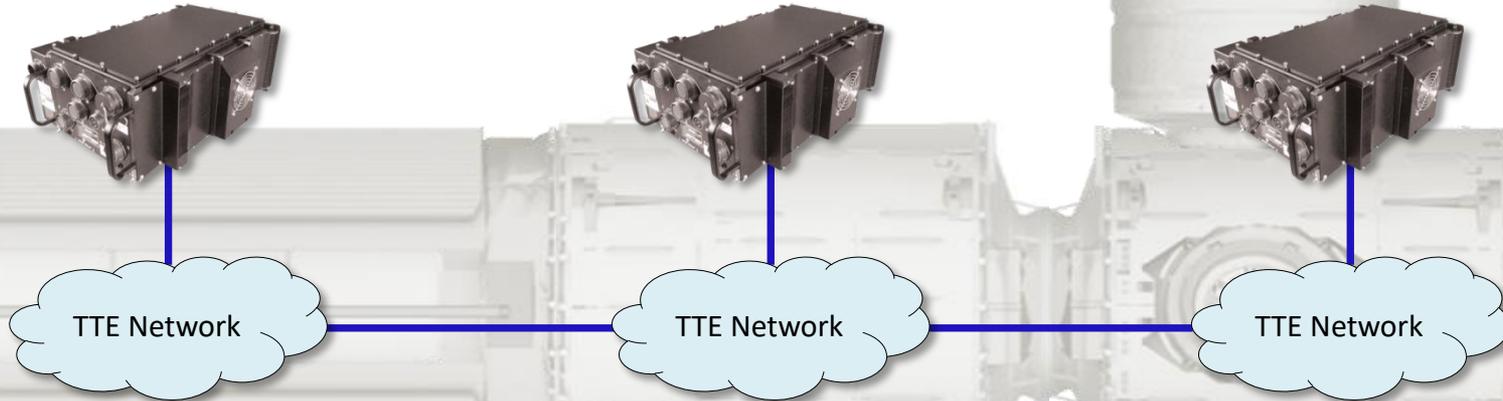
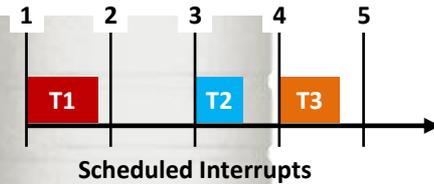
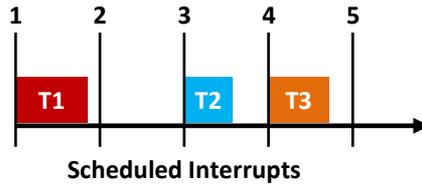
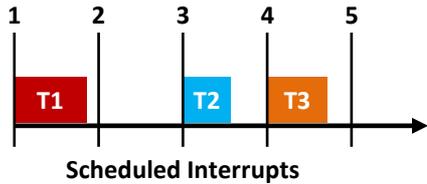


... That guarantee certain properties about the integrated system:

1. Composability
2. Compositionality

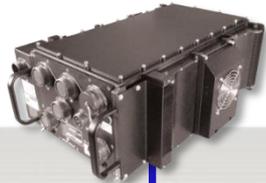
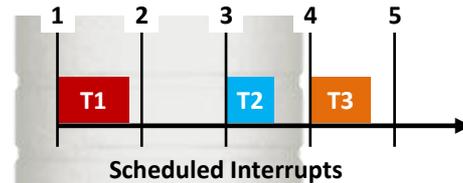
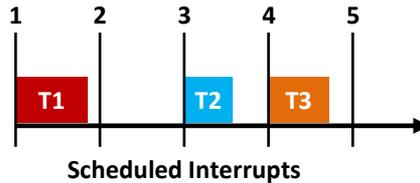
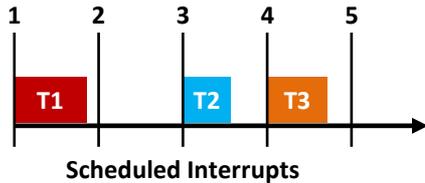
# Scheduled Execution

- Schedule interrupts based on global synchronized clock
- Cross-platform alignment between task scheduling and TT network scheduling



# Scheduled Execution

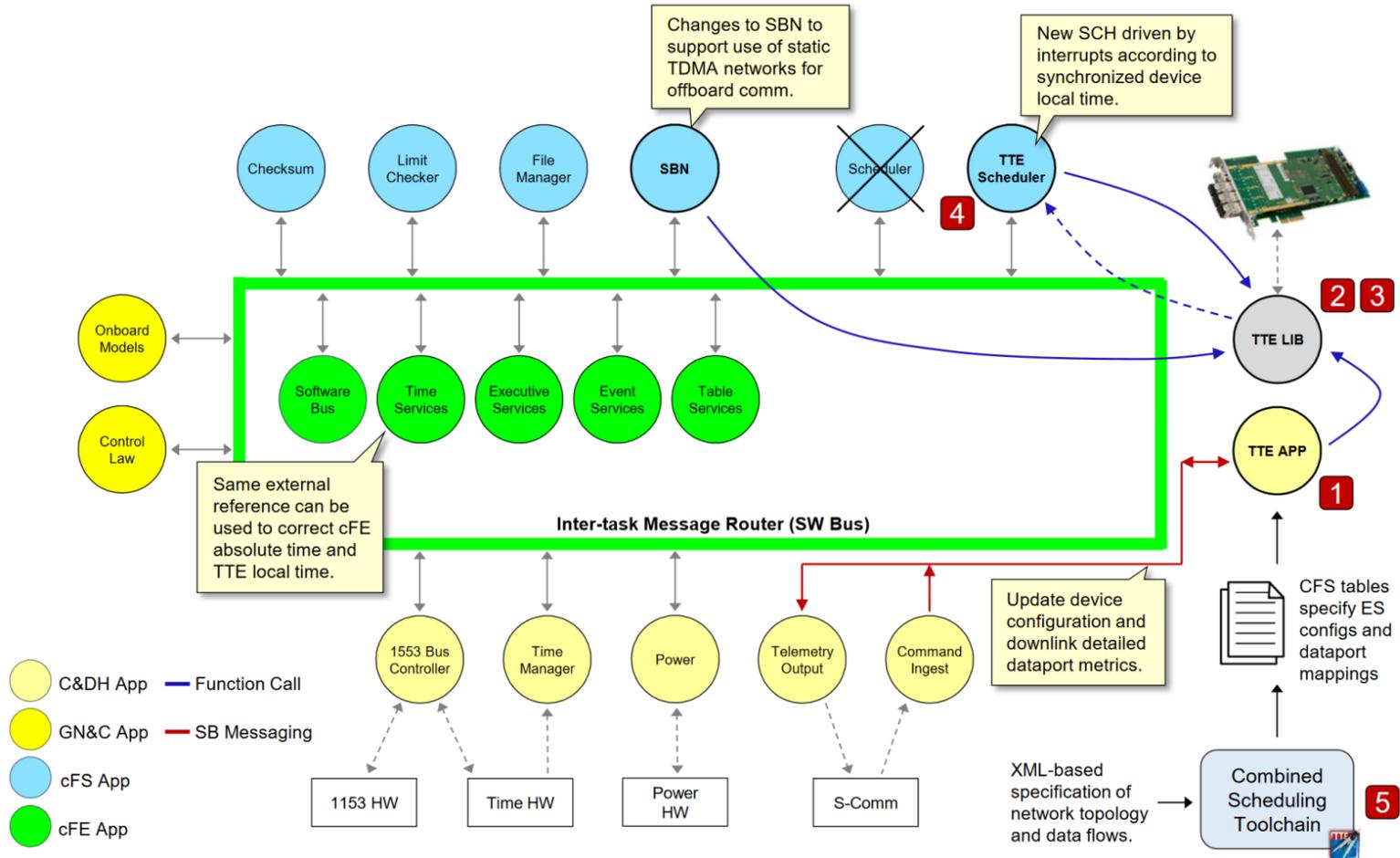
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TTE Network

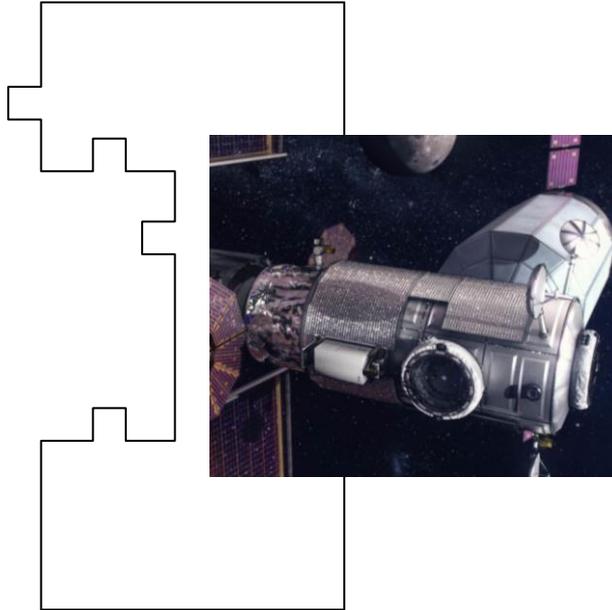
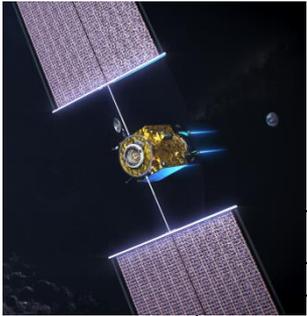
- Worst case contention and bandwidth utilization is known
- No need to overprovision FSW, SW, and ES buffers
- Benefits even with event-driven traffic

# Scheduled Execution: cFS

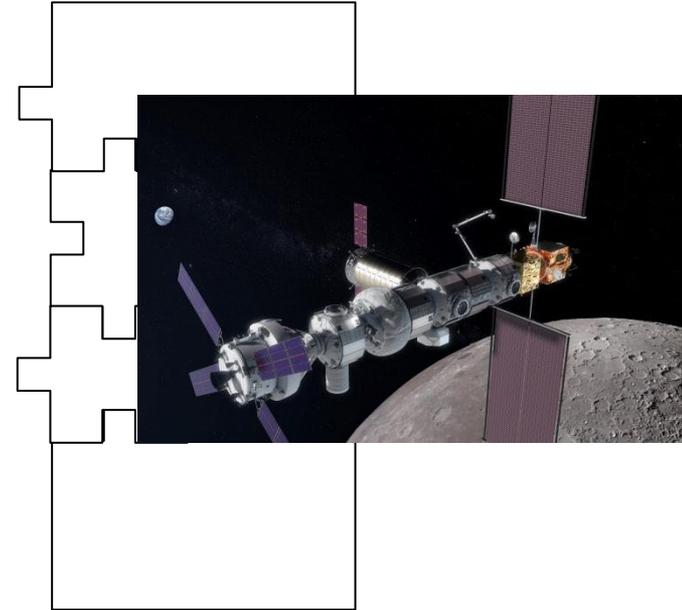


# Composable Systems

Because we know how these  
behave in isolation ...



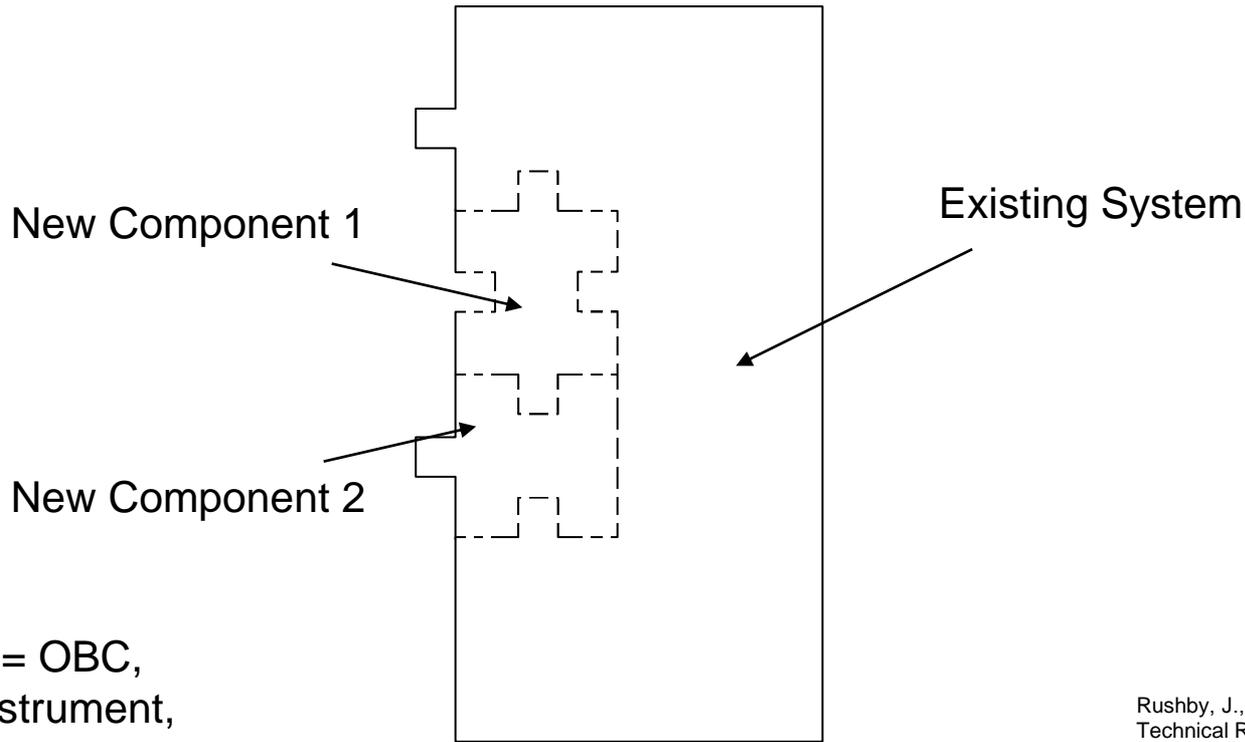
We know how this behaves  
when fully integrated



Module Integration

# Composable Systems

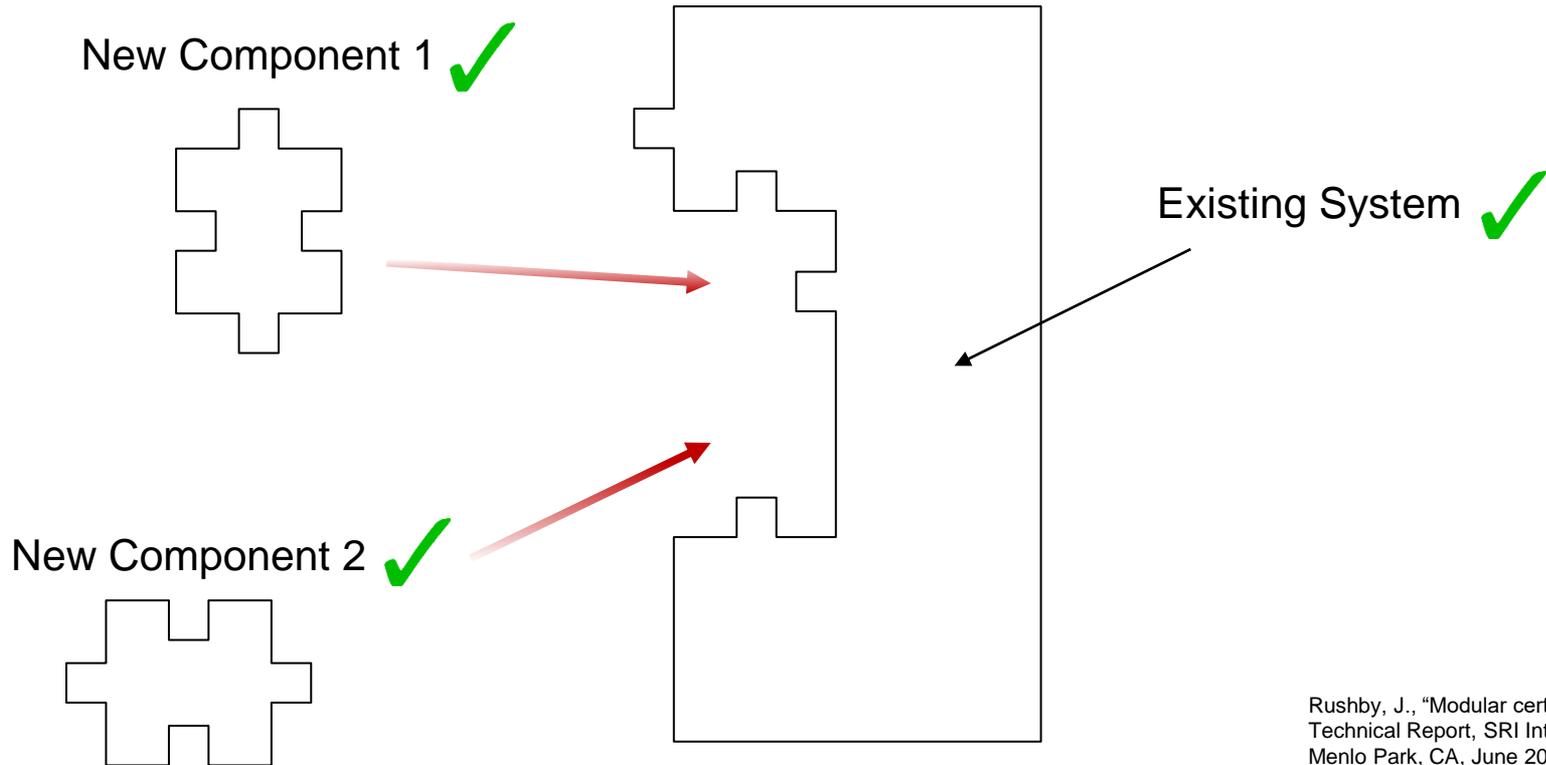
- Certification traditionally requires us to view the system as an indivisible whole



Component = OBC,  
Software, Instrument,  
Subsystem, Function

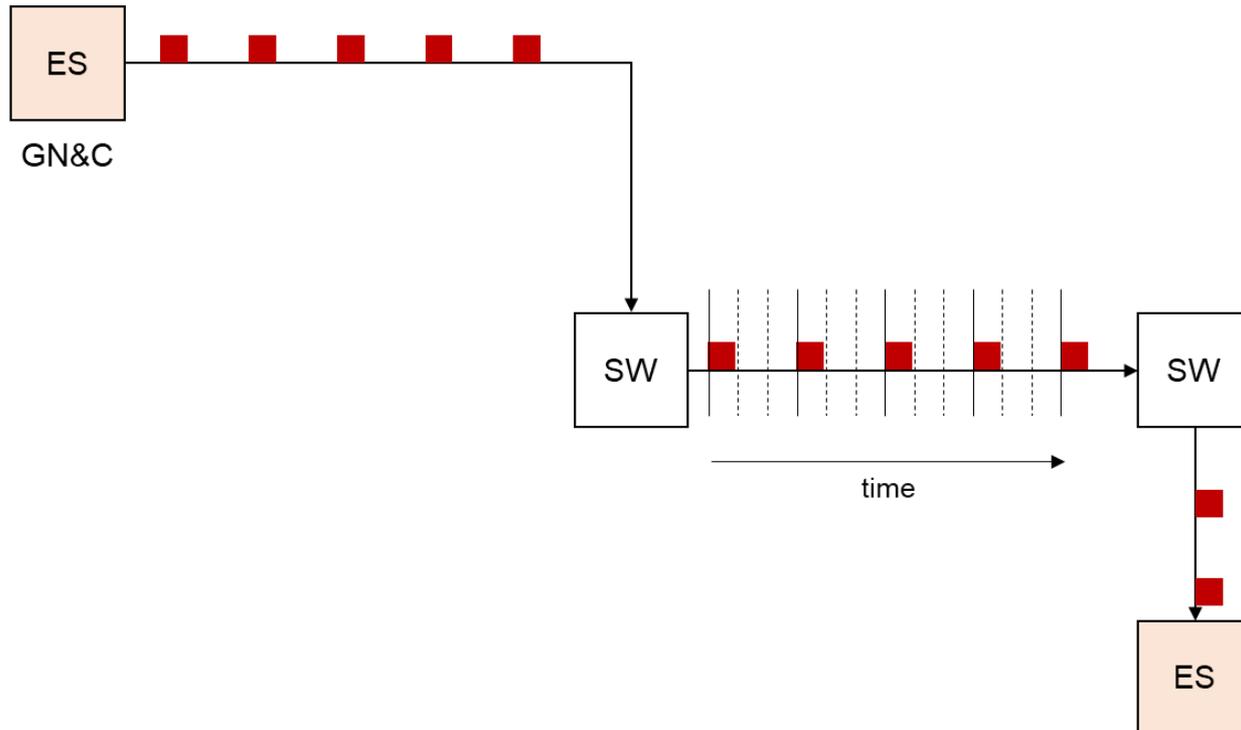
# Composable Systems

- Desirable to certify the whole by integrating smaller certified components



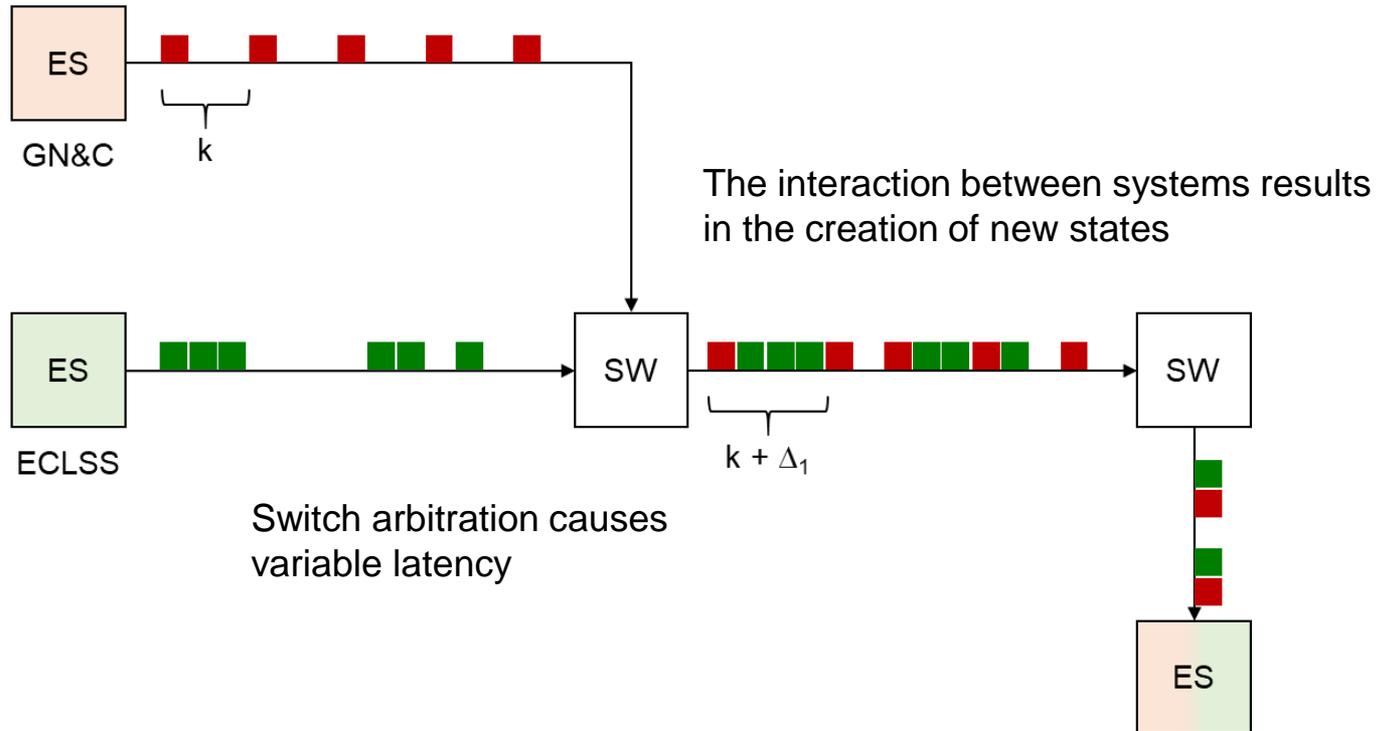
# Why is it Hard?

- Network traffic between modules can interact in unanticipated ways
- Makes it impossible to consider modules in isolation



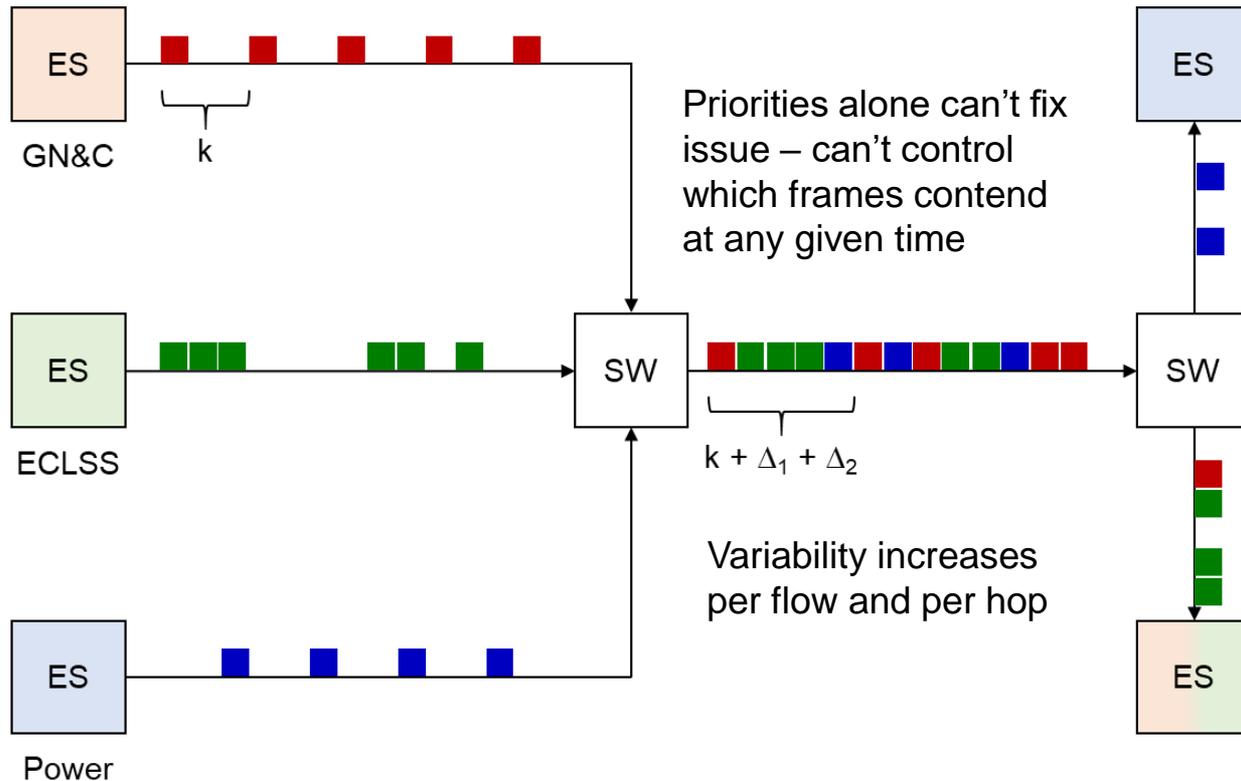
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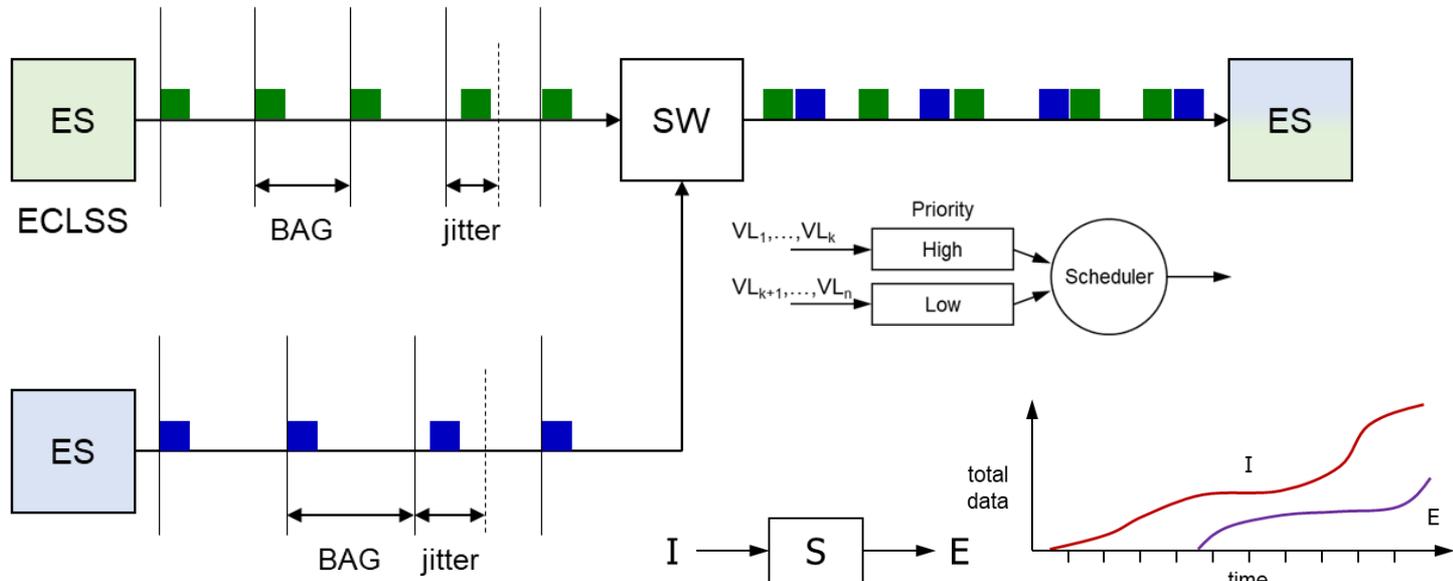
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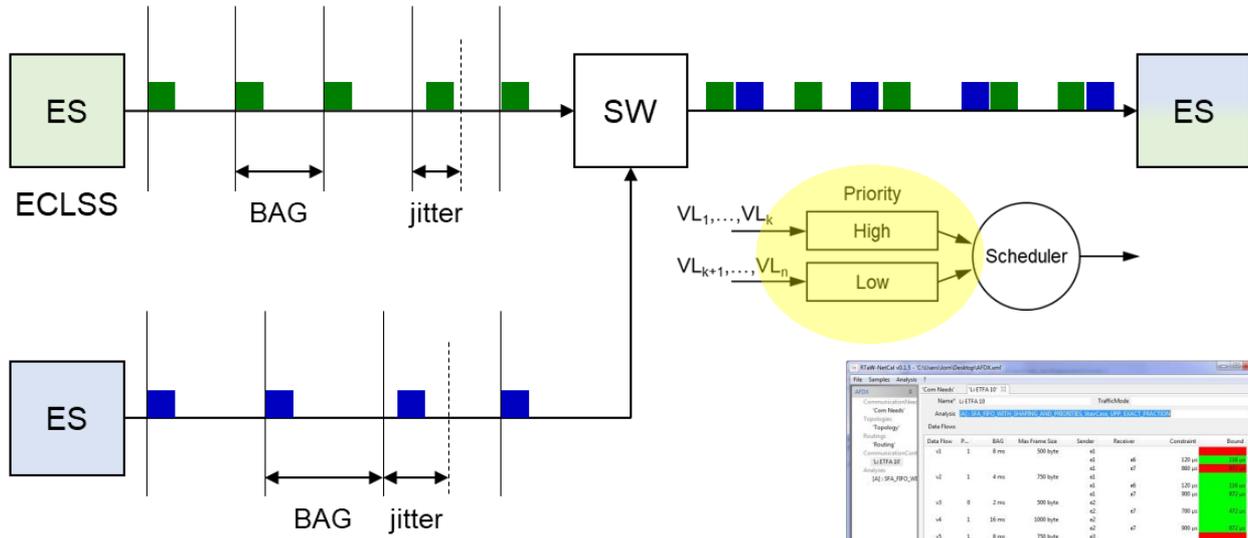
# One Approach: A664 P7

- **Bounding Variability:** ARINC 664 P7 can bound by mathematical proof:
  - 1) per VL end-to-end delay, 2) per port/VL jitter, 3) buffer sizes (from port waiting times)
- Use network calculus to calculate bounds on latency and queue sizes
  - Then use those metrics to determine VL priorities, BAGs, and frame sizes

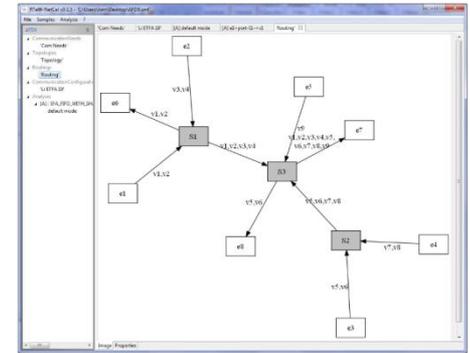


# One Approach: A664 P7

- But changing the priority or BAG of a given VL could have little impact, or huge impact
  - Depends not only on that VL, but what it contends with
- Therefore still requires consideration of the entire integrated system
- Increases complexity of maintaining a network that needs to grow/evolve over time

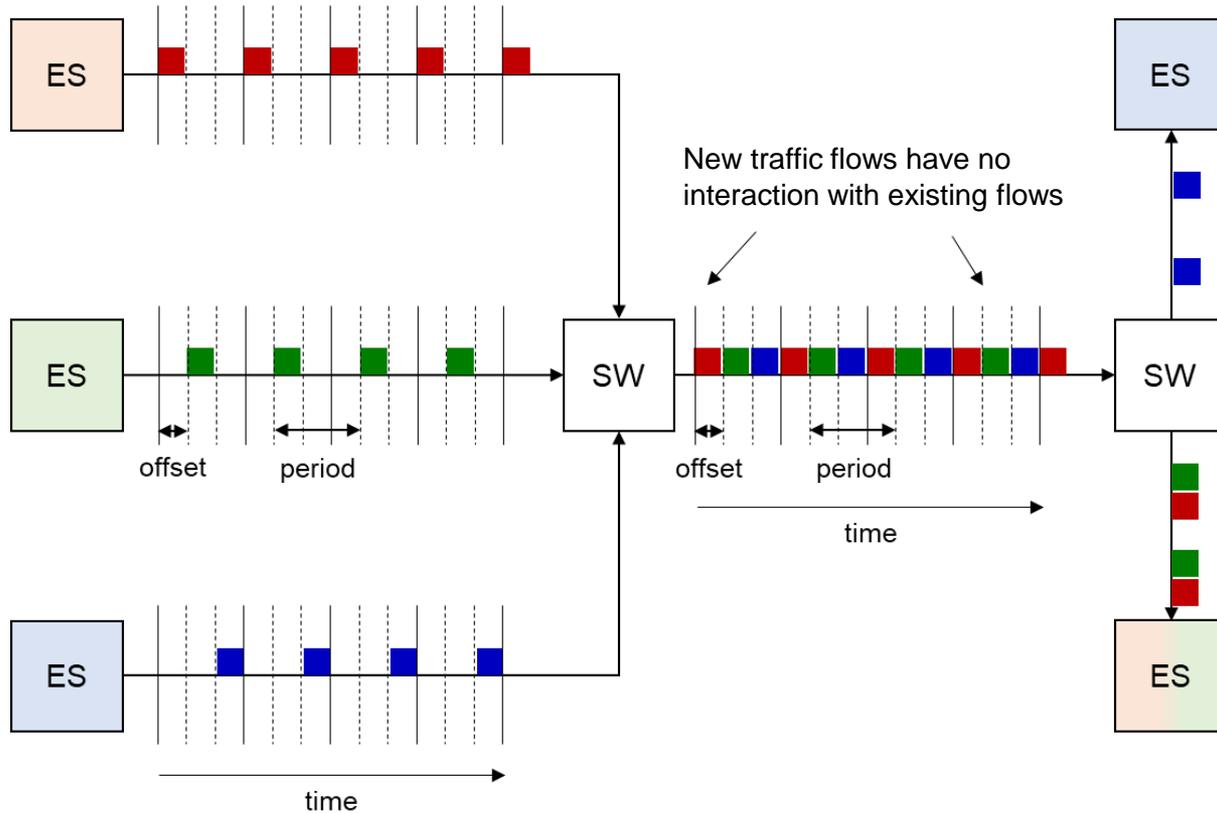


Data Flow	P.	BAG	Max Frame Size	Sender	Receiver	Constraint	Bound
v1	1	8ms	500 bytes	e1	e6	120 μs	120 μs
v2	1	4ms	750 bytes	e1	e7	800 μs	800 μs
v3	8	2ms	500 bytes	e2	e7	120 μs	120 μs
v4	1	16ms	1000 bytes	e2	e7	800 μs	800 μs
v5	1	8ms	750 bytes	e3	e7	300 μs	300 μs
v6	8	2ms	500 bytes	e3	e8	800 μs	800 μs
v7	8	32ms	1000 bytes	e4	e7	1000 μs	1000 μs
v8	1	16ms	750 bytes	e4	e7	800 μs	800 μs



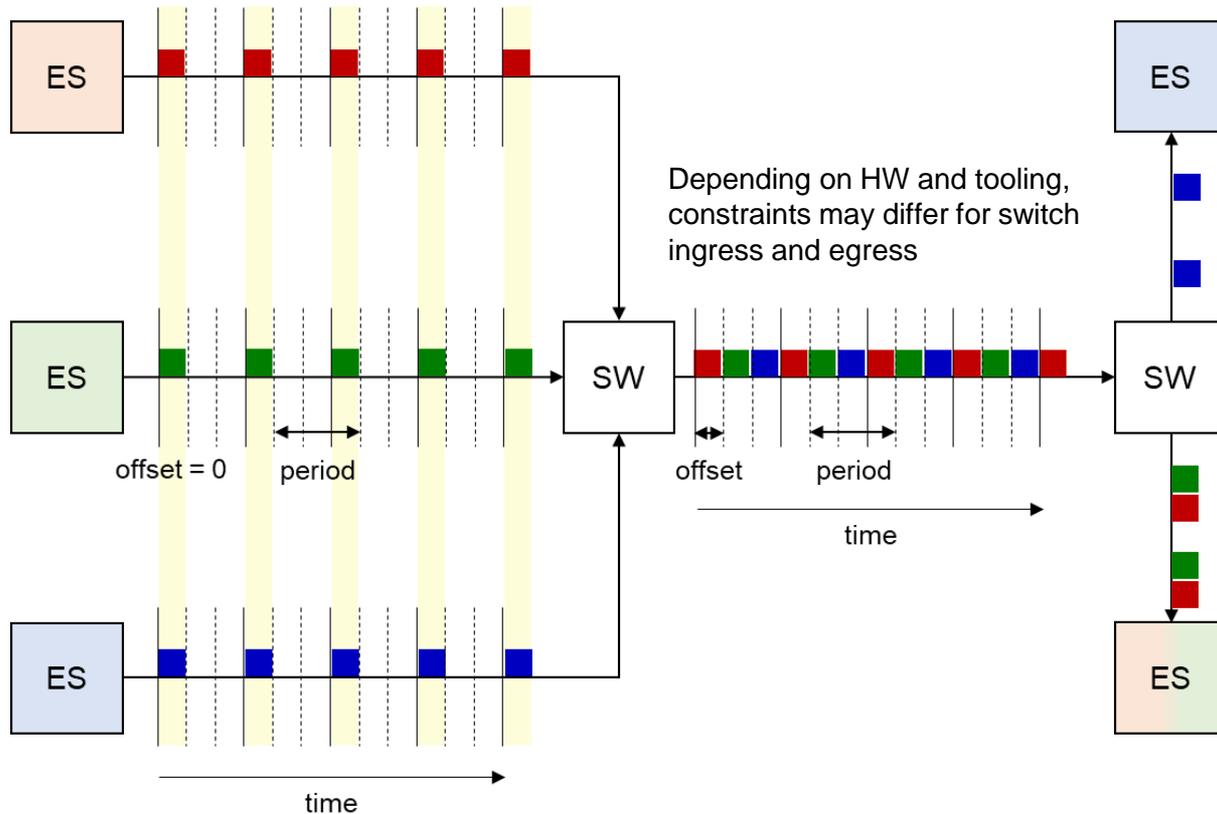
# Alternative Approach: TTE

- Prevent the contention that causes the timing variability (e.g. for buffers, ports)



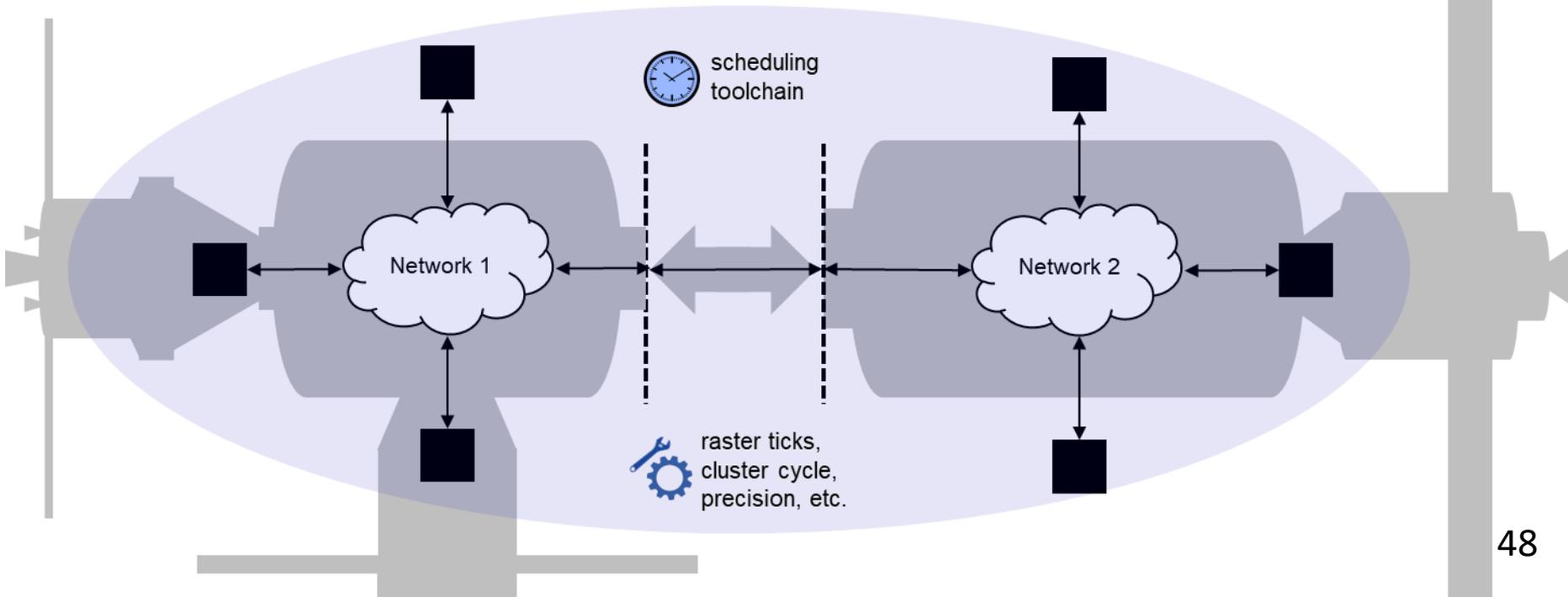
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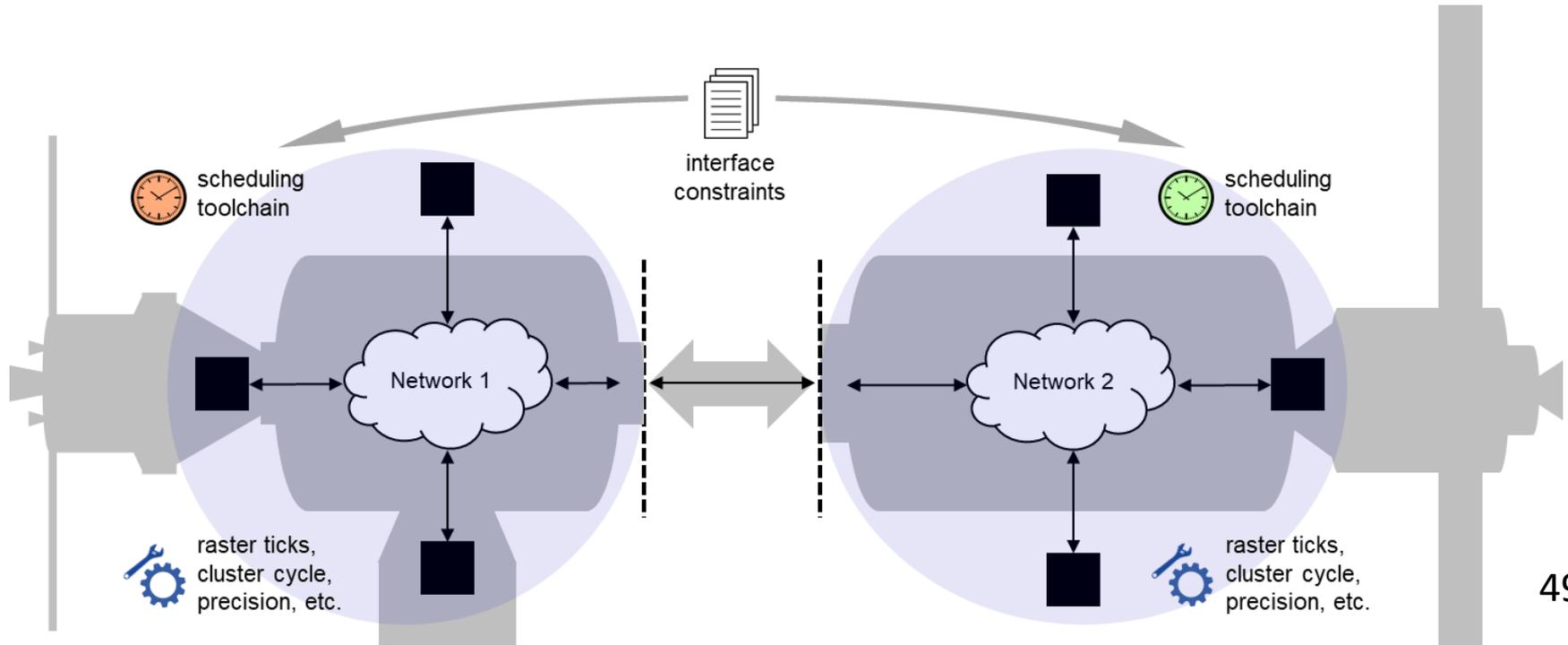
# Incremental Buildup

- **One Option:** Schedule the whole integrated vehicle at once
  - x Not composable - schedule change in one module could necessitate change in another
  - x Requires the same tooling for all Gateway modules



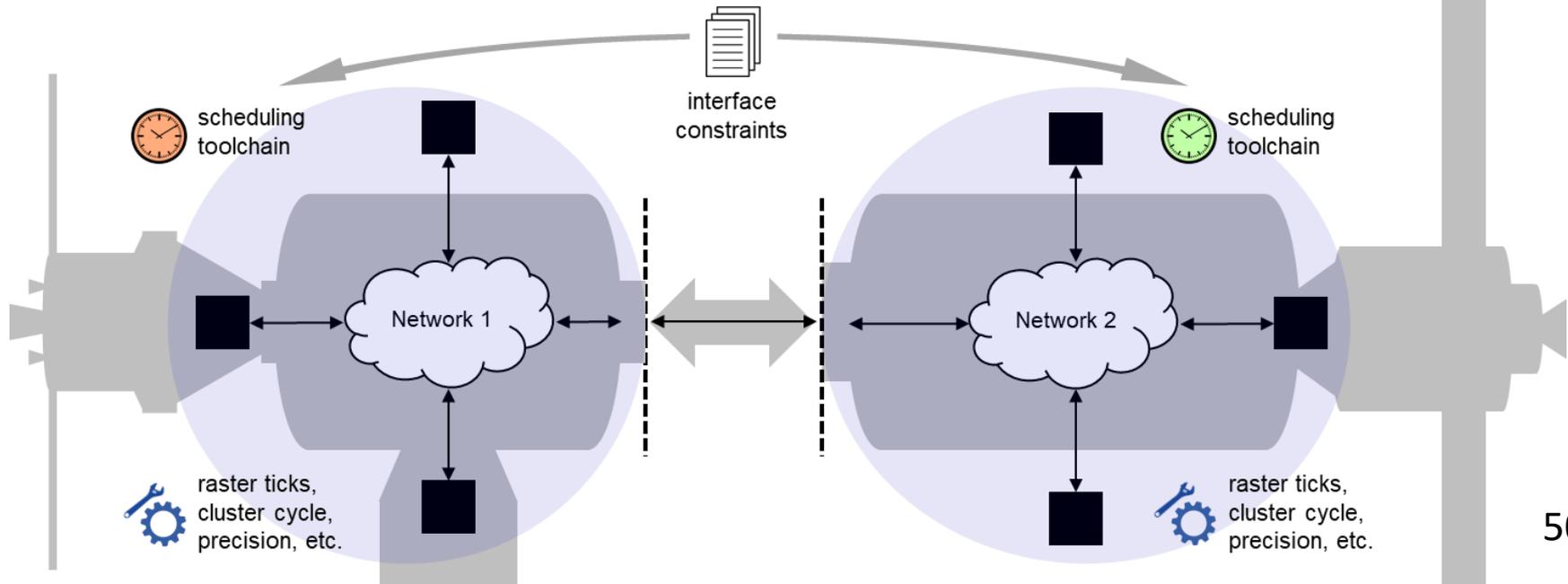
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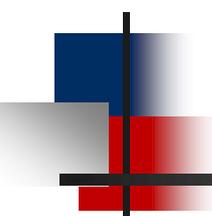
- **Another Option:** Vehicle has one network, scheduled piecewise with different tooling
  - Agree on consistent timing parameters for each module (e.g. raster granularity, cluster cycle, precision)
  - Define message properties at every module interface (e.g. direction, timing, max size)
  - Use these properties as constraints for scheduling each module



# Incremental Buildup

- **Another Option:** Vehicle has one network, scheduled piecewise with different tooling
  - ✓ Scheduling can be done separately per module (potentially with different tooling)
  - ✓ Scheduling within a module must only change if the interface constraints change
  - ✓ Allows different modules to be tested independently – interactions are completely controlled
  - ✗ Messaging constraints at interface must be identified up front





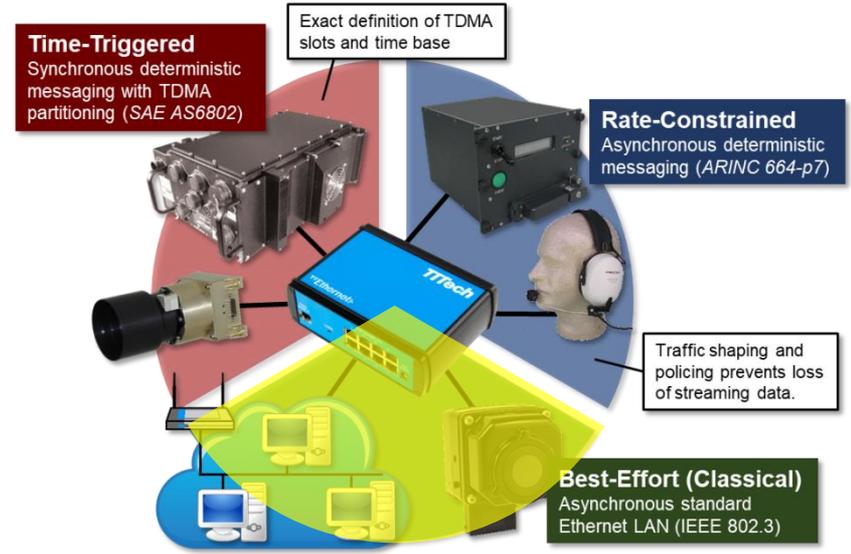
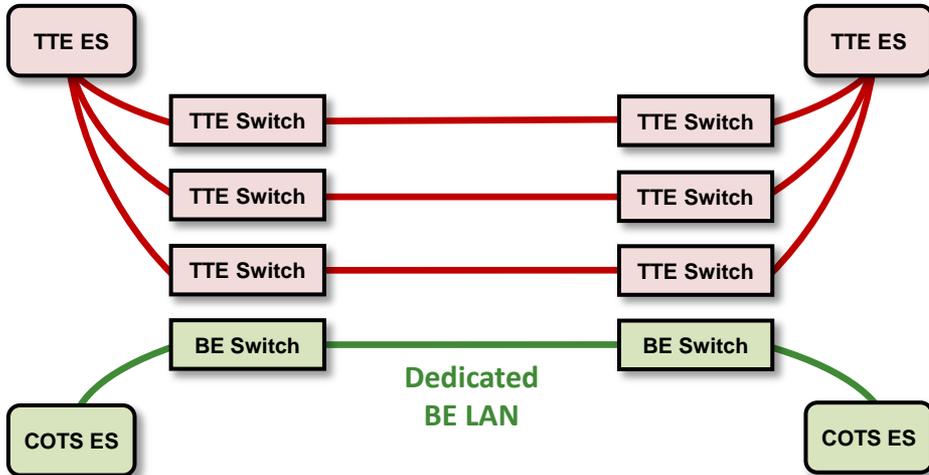
# Agenda

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- Introduction to Gateway
- Time-Triggered Ethernet (TTE) backbone
- TTE, A Fault-Tolerant Interconnect
- TTE, An Integration Framework
- **A Unique Challenge, Classical Ethernet**
- Conclusion

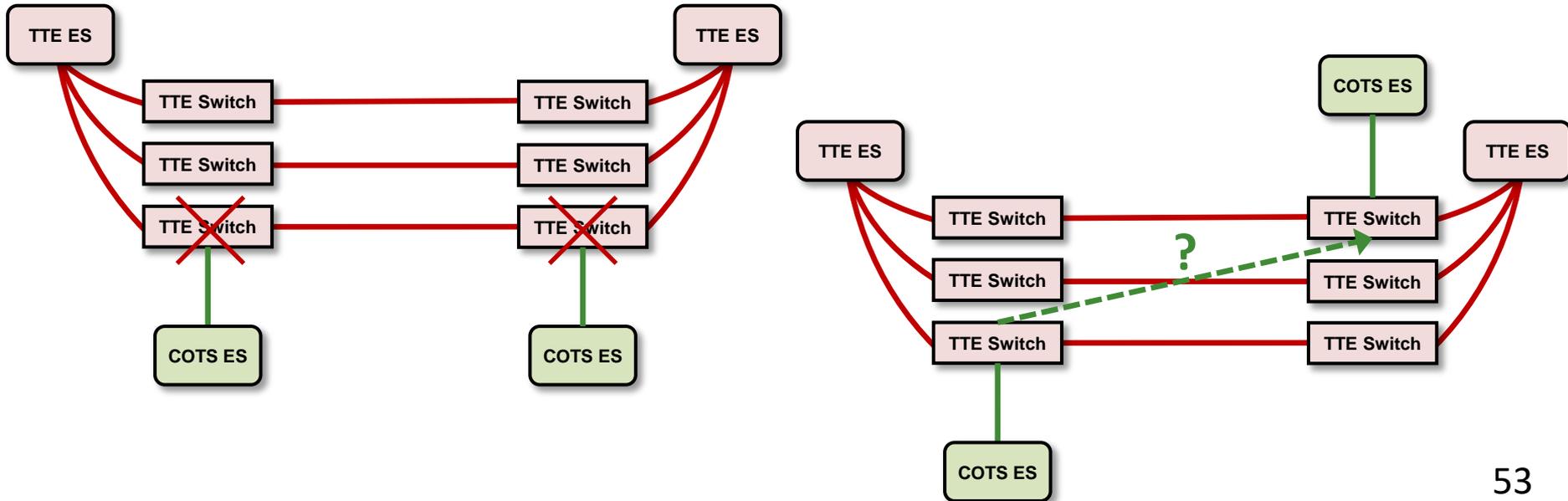
# Best-Effort Ethernet

- Gateway has **no dedicated** best-effort plane
  - Standard Ethernet/COTS devices connect to the same TTE network
  - Supported by TTE standard – should be no problem



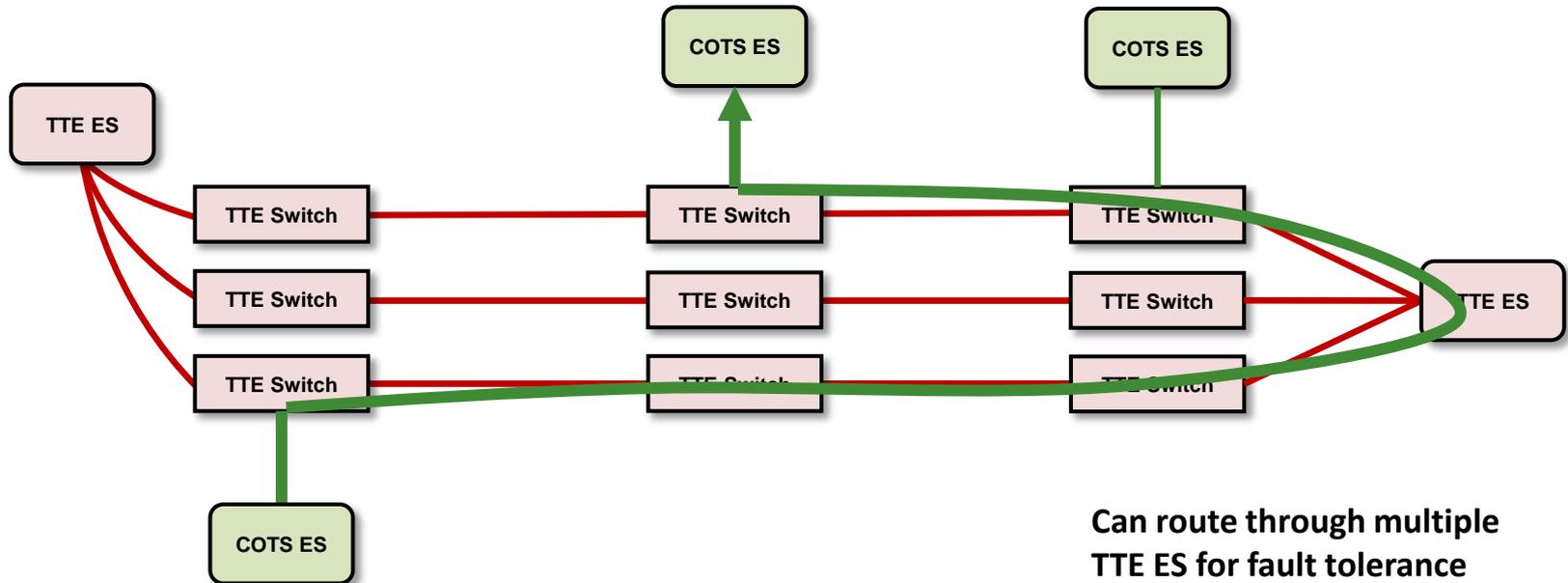
# Best-Effort Ethernet

- **A Challenge:** Many COTS devices only connect to one plane
  - If all COTS devices are on same plane, you lose them after one fault
    - Some “non-critical” devices are critical. E.g. Cameras, crew laptops
  - But if COTS devices are on different planes, how do they talk?



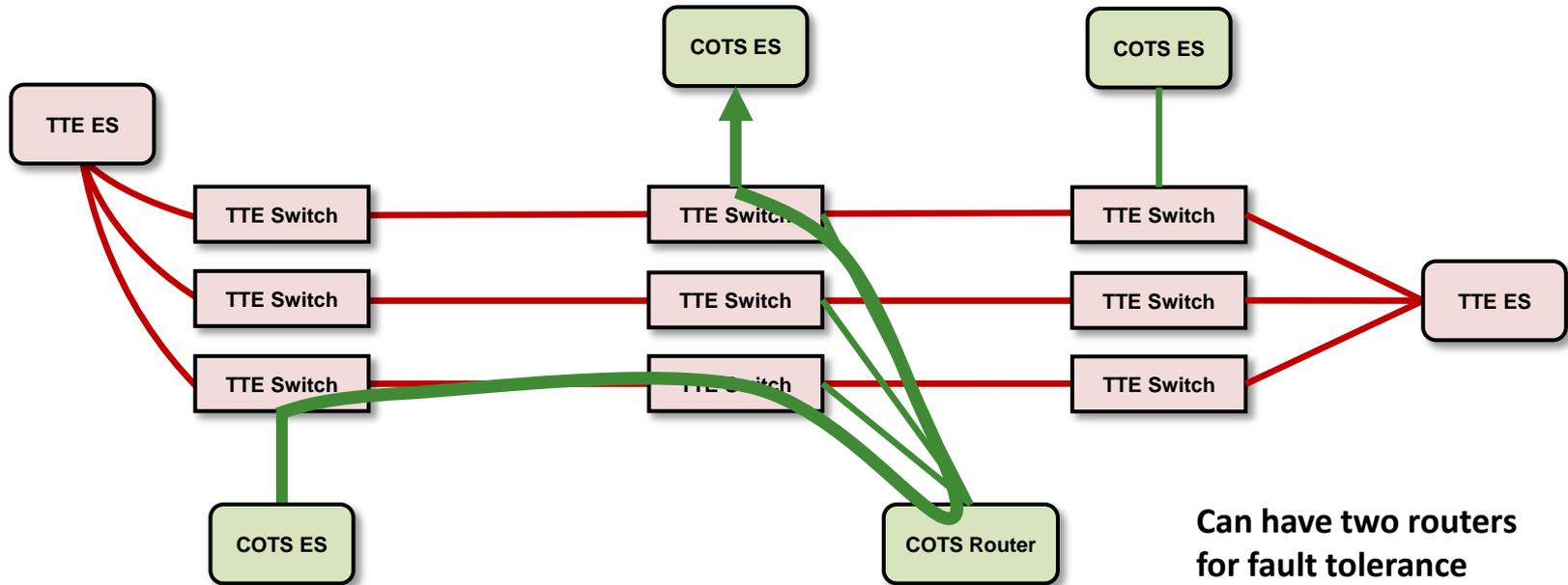
# A Few Options

- Retransmit frames through a TTE end system
  - **Pros:** Adds no SWaP, needs no switch ports
  - **Cons:** Needs extra CPU time, SW changes, custom routing rules



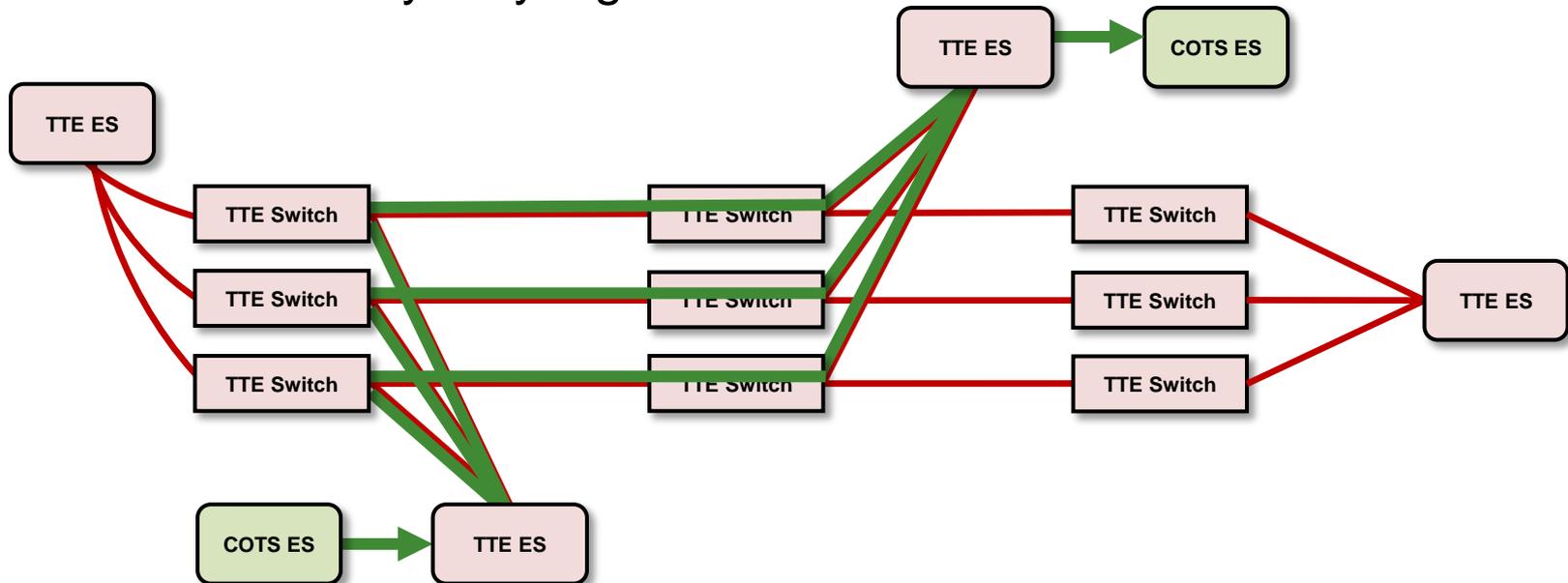
# A Few Options

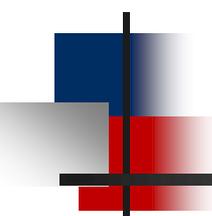
- Add a separate device to route frames
  - **Pros:** No SW changes, can use COTS routers
  - **Cons:** Adds SWaP, needs more switch ports, higher layers (L3+)



# A Few Options

- Connected devices through a remote interface unit (RIU)
  - **Pros:** Can convert BE to TT/RC, increases availability of BE, reduces switch ports on main backbone
  - **Cons:** Potentially very high SWaP

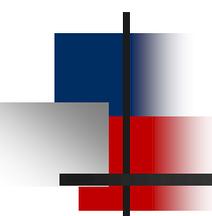




# Best-Effort Ethernet

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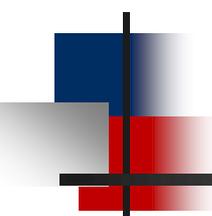
- **Takeway:** No single best way to integrate COTS devices with a multi-plane TTE network
- Fact that TTE supports best-effort Ethernet is only part of the battle



# Agenda

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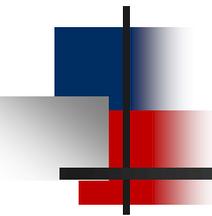
- Introduction to Gateway
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# Conclusion

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- Gateway is based on a redundant TTE backbone
- TTE allows mixed-criticality traffic to exist on same network
- TTE can be used to realize a reliable broadcast abstraction
- TTE should be thought of as an integration framework
- Using COTS devices on TTE is not fool proof



# Sources

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## Content

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## Images

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